



DAKOTA 5.0 and JAGUAR 2.0

Capability Overview

(based on January 2010 briefings)

Brian Adams

DAKOTA Project Lead

Optimization and Uncertainty Quantification (1411)



DAKOTA Overview Goals



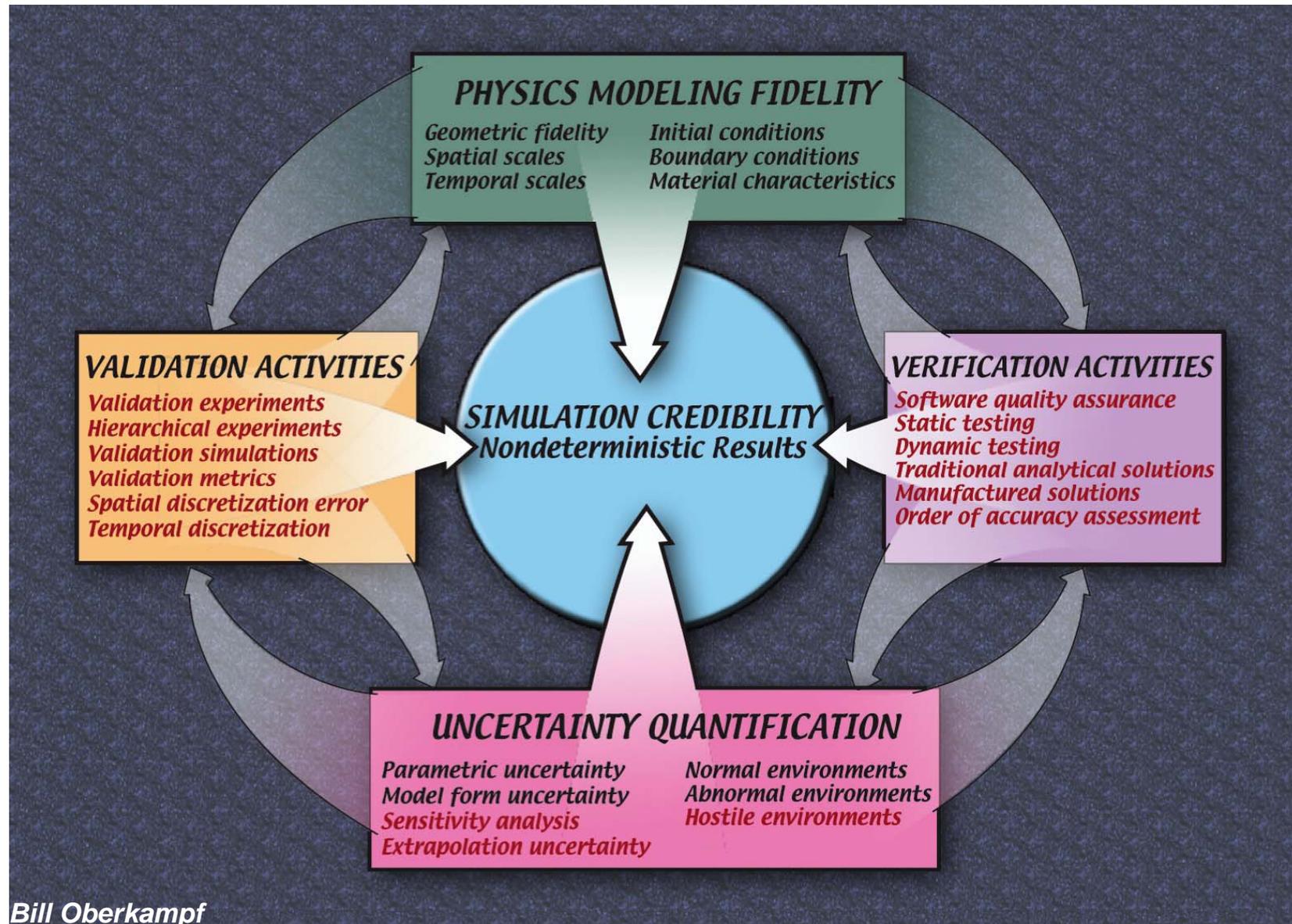
GOAL: Help you decide if DAKOTA might be relevant for your work

- **Overview of DAKOTA and usage examples (20 min)**
 - Overview, key capabilities
 - Four categories of methods
 - Advanced capabilities
- **New features in DAKOTA 5.0; training sessions (10 min)**
- **Demonstration of JAGUAR 2.0 GUI (20 min)**

Formal V&V, UQ, and Model Fidelity Support Credible Simulation



Ultimate purpose (arguably): insight, prediction, and risk-informed decision-making → *need credibility for intended application*



DAKOTA in a Nutshell



Design and Analysis toolKit for Optimization and Terascale Applications includes a wide array of algorithm capabilities to support engineering transformation through advanced modeling and simulation.

Adds value to simulation-based analysis by answering fundamental science and engineering questions:

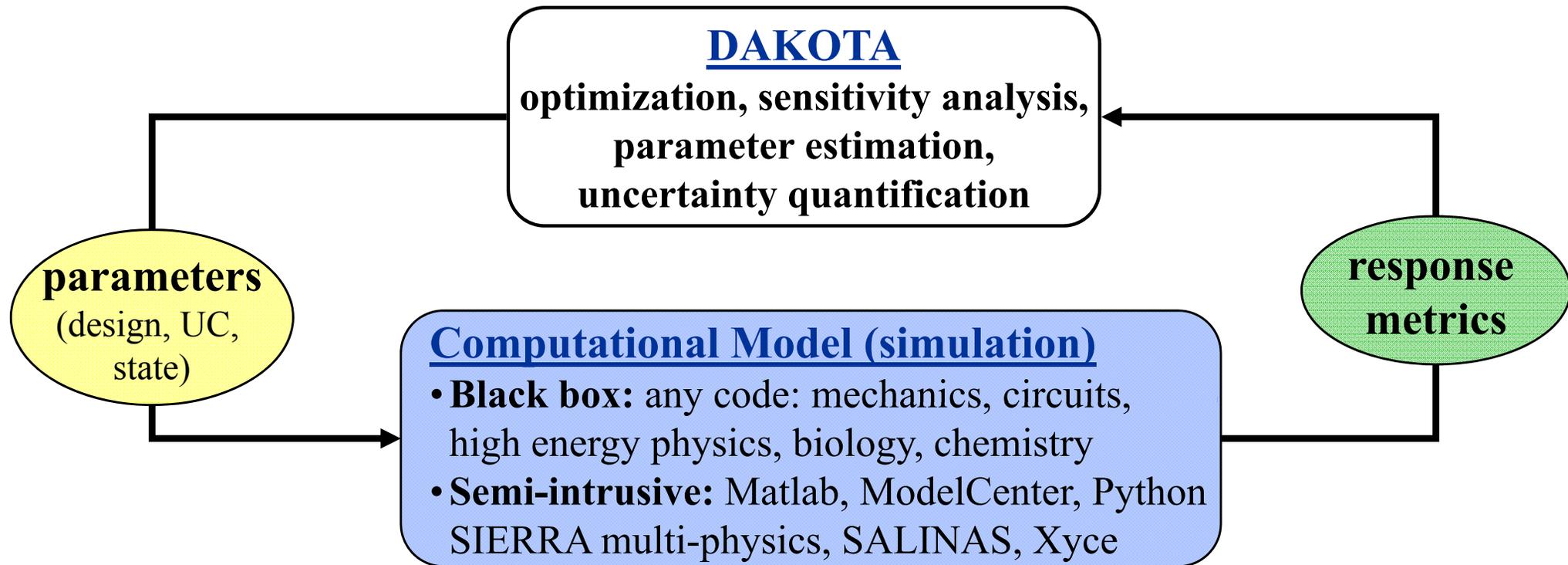
- **What are the crucial factors/parameters and how do they affect key metrics? (*sensitivity*)**
- **How safe, reliable, robust, or variable is my system? (*quantification of margins and uncertainty: QMU, UQ*)**
- **What is the best performing design or control? (*optimization*)**
- **What models and parameters best match experimental data? (*calibration*)**

- ***All rely on iterative analysis with a computational model for the phenomenon of interest***

Automated Iterative Analysis



Automate typical “parameter variation” studies with a generic interface to simulations and advanced methods

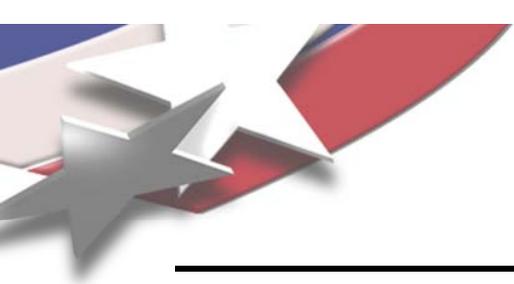


- **Can support experimental testing:** examine many accident conditions with computer models, then physically test a few worst-case conditions.

Key DAKOTA Capabilities



- **Generic interface** to simulations
- **Time-tested and advanced algorithms** to address nonsmooth, discontinuous, multimodal, expensive, mixed variable, failure-prone
- **Strategies to combine methods** for advanced studies or improve efficiency with surrogates (meta-models)
- Mixed **deterministic / probabilistic** analysis
- Supports **scalable parallel computations** on clusters
- Object-oriented code; modern software quality practices
- Limited Windows interface (run via command prompt); **however new graphical user interface. DART integration in progress.**
- **Additional details:** <http://www.cs.sandia.gov/dakota>
 - Extensive documentation, including a tutorial
 - Support mailing lists
 - Software downloads: stable releases and nightly builds (freely available worldwide via GNU LGPL)



DAKOTA Team



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- John Sirola (1433)



DAKOTA Overview Goals



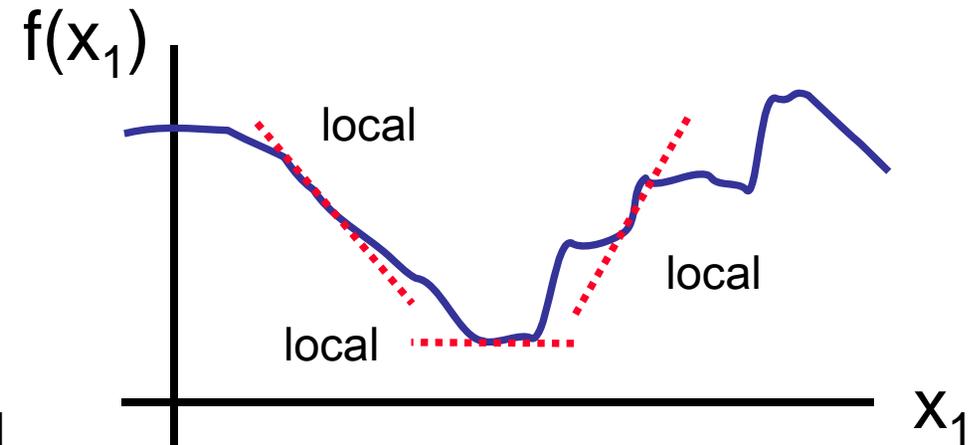
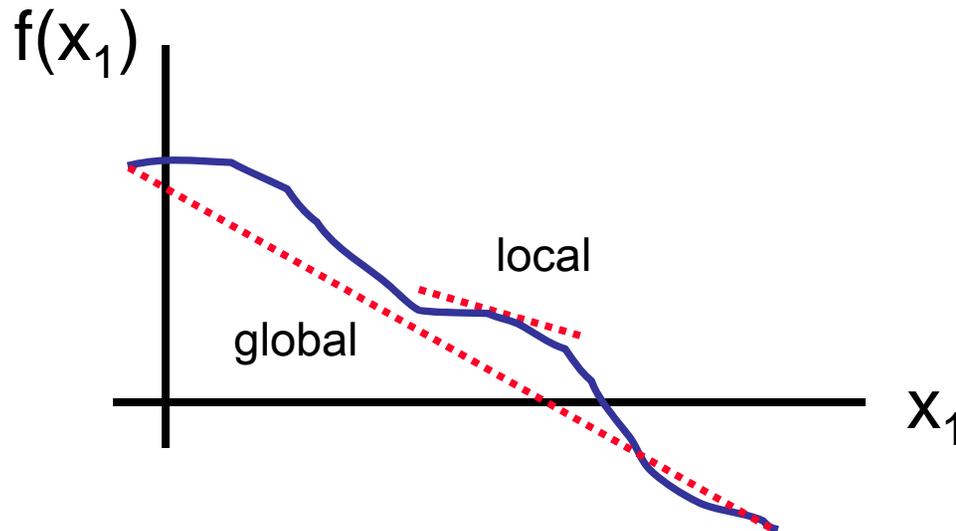
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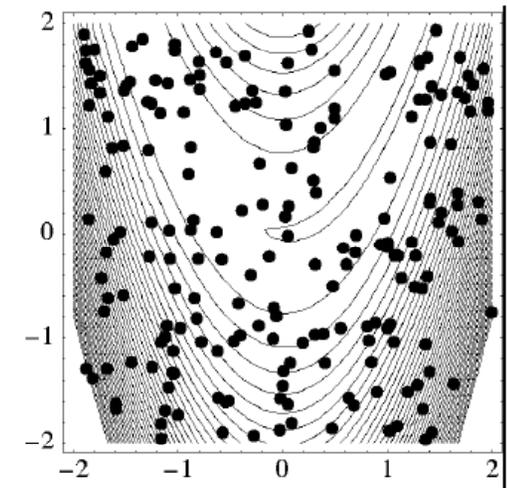
Sensitivity Analysis



How do code outputs vary due to changes in code inputs?



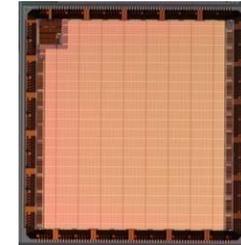
- **Sensitivity analysis examines variations in $f(x_1)$ due to perturbations in x_1**
 - Local sensitivities are typically partial derivatives (given a specific x_1 , what is the slope at that point?)
 - Global sensitivities are typically found via sampling methods and regression (what is the trend of the function over all values of x_1 ?)
- **Determines which variables are important to perform optimization or UQ on, or which to gather more data on or control in an experiment.**



SA for Electrical Circuits

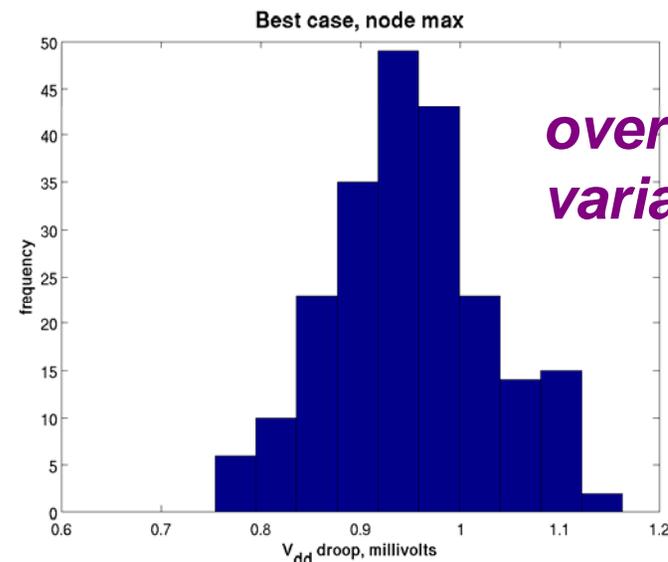


- **CMOS7 ViArray**: generic ASIC implementation platform; *applications in NW, satellite, command & control*
- Modeling and simulation used in design phase to assess predicted performance during photocurrent event, including sensitivity/variability of supply voltage
- DAKOTA coupled to Xyce circuit simulator to **determine which process layers contributed most to device performance** (1000s of simulation runs, each 2.0h to 4.5h)

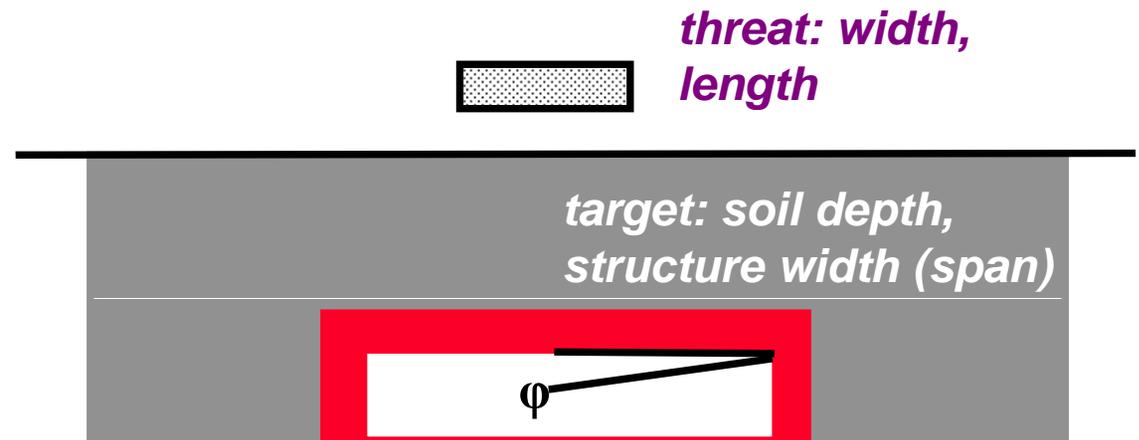
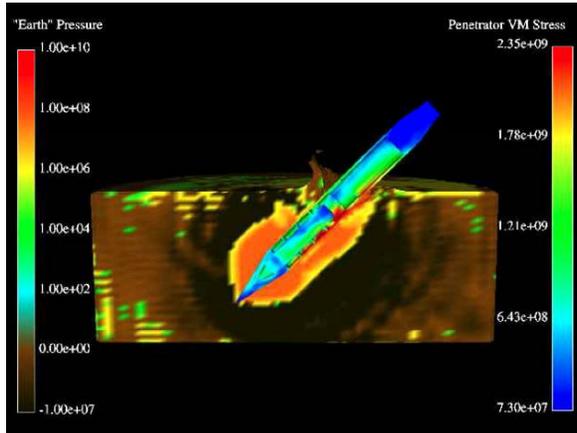


	Vdd Metrics	
	node max	node avg
METAL1	0.96	0.82
METAL2	0.11	0.04
METAL3	0.10	0.05
METAL4	0.80	0.81
METAL5	0.86	0.91
VIA1	0.71	0.66
VIA2	0.80	0.76
VIA3	0.57	0.60
VIA4	0.91	0.94
CONTACT	0.21	0.13
polyc	0.04	0.05

correlations

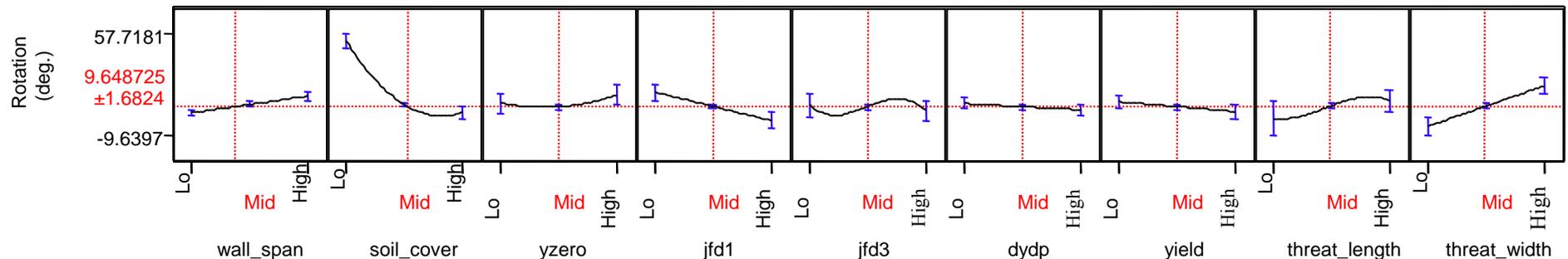


SA of Penetrator



Notional model for illustration purposes only
(<http://www.sandia.gov/ASC/library/fullsize/penetrator.html>)

- **Underground target with external threat:** assess uncertainty in target response given uncertainty in target construction and threat characteristics
- 12 parameters describing target & threat uncertainty
- Response: angular rotation (ϕ) of target roof at mid-span
- Analysis: CTH Eulerian shock physics code; JMP stats



DAKOTA Sensitivity Analysis

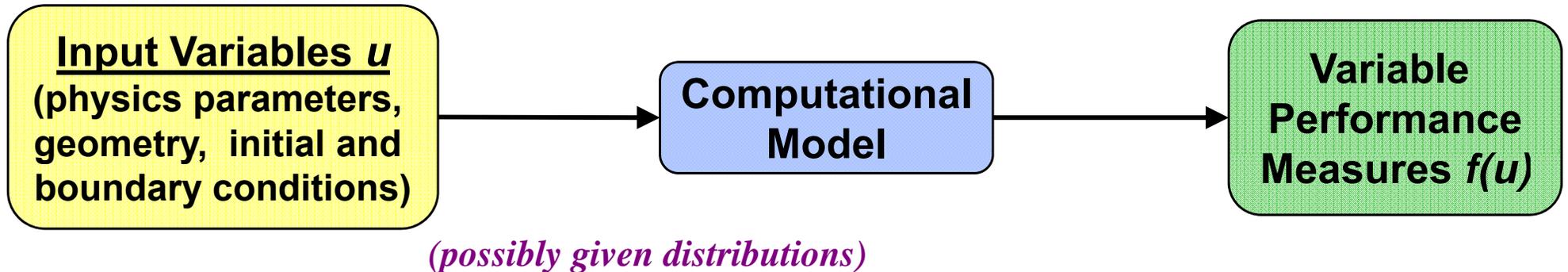


- **Parameter study, design and analysis of computer experiments, and general sampling methods:**
 - Single and multi-parameter studies (grid, vector, centered)
 - DDACE (grid, sampling, orthogonal arrays, Box-Behnken, CCD)
 - FSUDACE (Quasi-MC, CVT)
 - PSUADE (Morris designs)
 - Monte Carlo, Latin hypercube sampling (with correlation or variance analysis, including variance-based decomposition)
 - Mean-value with importance factors
- **DAKOTA outputs basic statistics on responses, including mean, standard deviation, and correlations; tabular output can be analyzed with any third-party statistics package**
- **Determine main effects and key parameter *interactions***
- **In SA, one typically does not make a distribution assumption**

Uncertainty Quantification

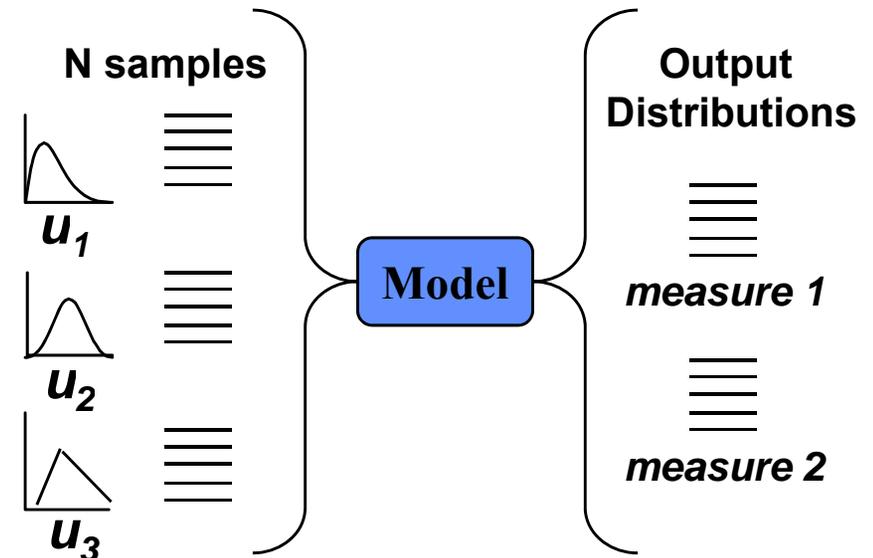


Forward propagation: quantify the effect that uncertain (nondeterministic) input variables have on model output



Potential Goals:

- based on uncertain inputs, determine **variance of outputs and probabilities of failure (reliability metrics)**
- identify parameter correlations/local sensitivities, robust optima
- identify inputs whose variances contribute most to output variance (global sensitivity analysis)
- quantify uncertainty when using calibrated model to predict

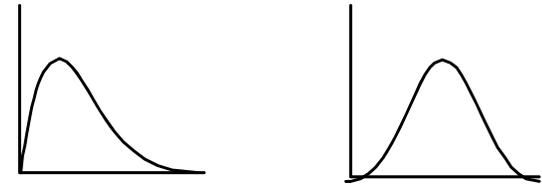
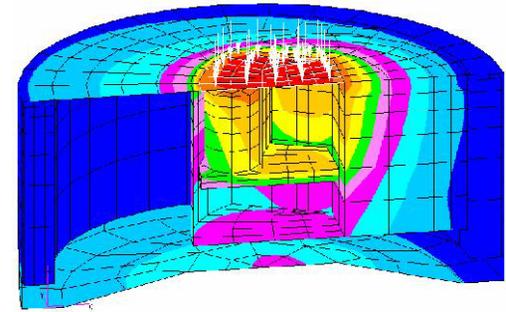


Typical method: Monte Carlo Sampling

Thermal Uncertainty Quantification



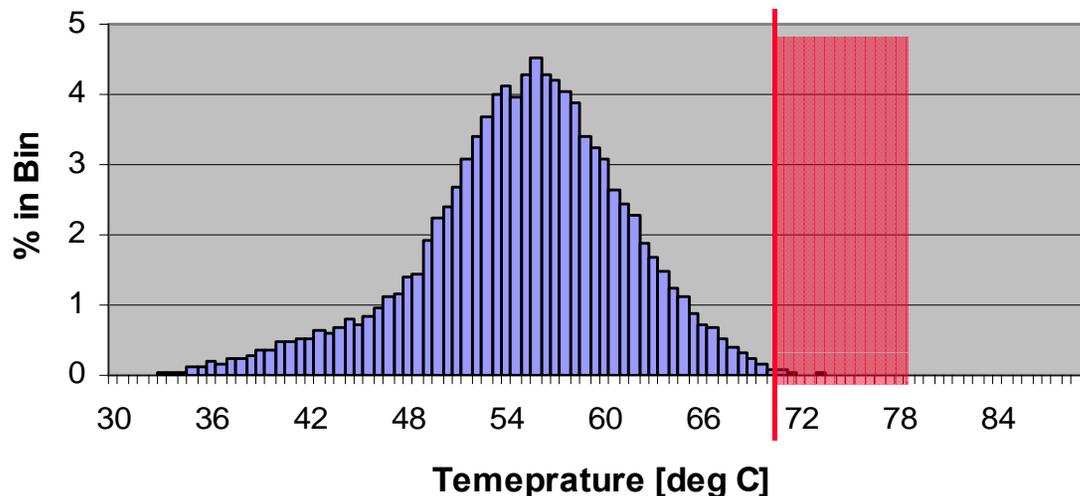
- **Device subject to heating** (experiment or computational simulation)
- **Uncertainty in composition/ environment** (thermal conductivity, density, boundary), parameterized by u_1, \dots, u_N
- **Response temperature** $f(u)=T(u_1, \dots, u_N)$ calculated by heat transfer code



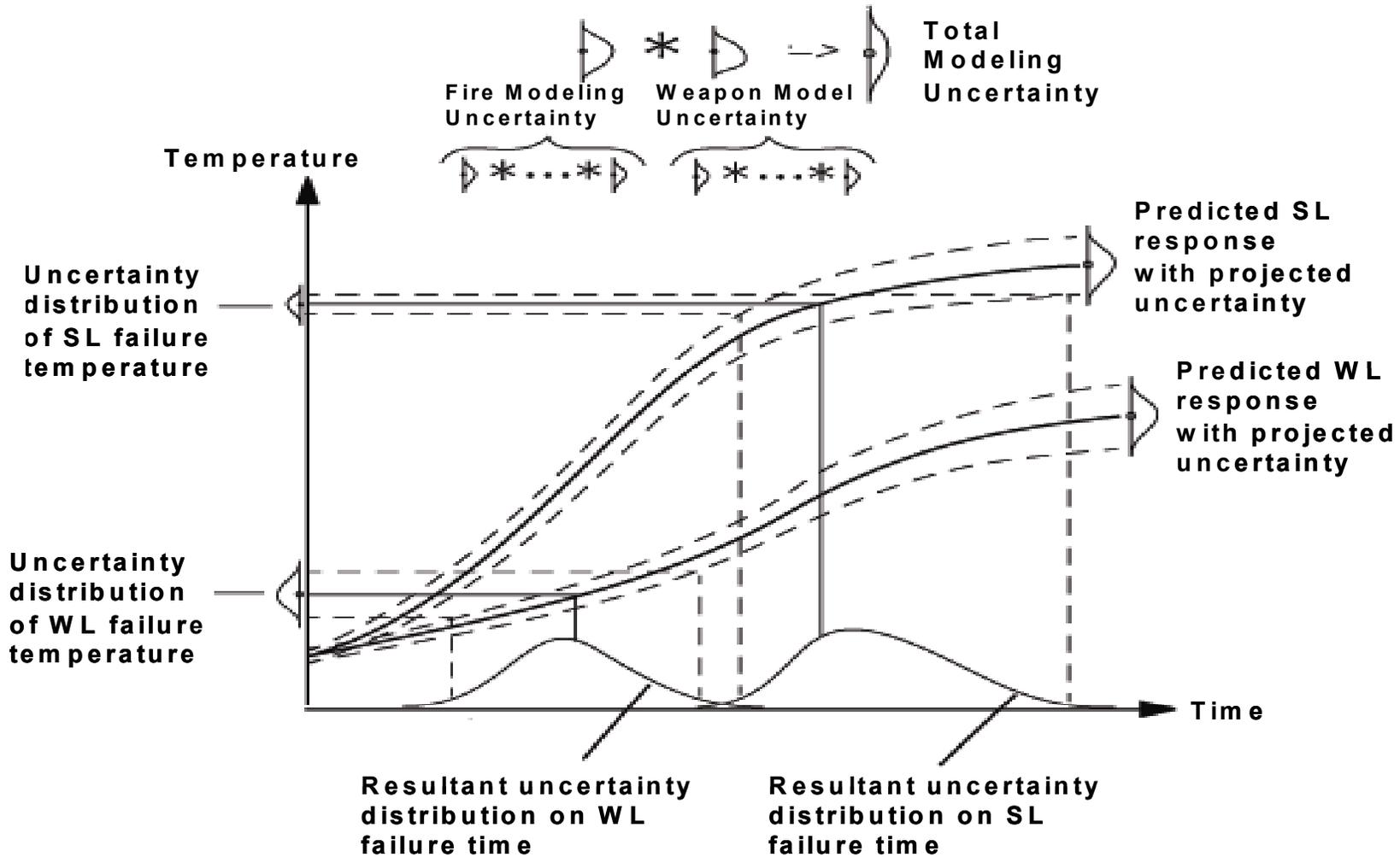
Given distributions of u_1, \dots, u_N , UQ methods calculate statistical info on outputs:

- **Mean(T), StdDev(T), Probability($T \geq T_{\text{critical}}$)**
- **Probability distribution of temperatures**
- **Correlations (trends) and sensitivity of temperature**

Final Temperature Values



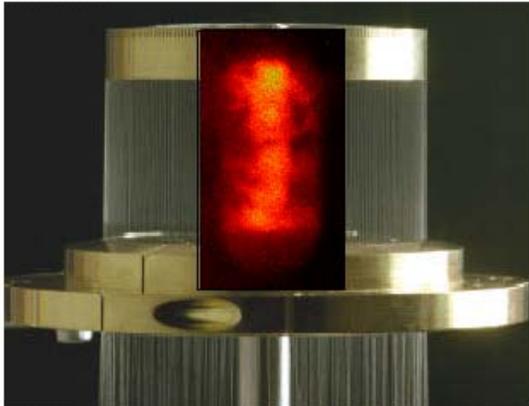
UQ for Thermal Race



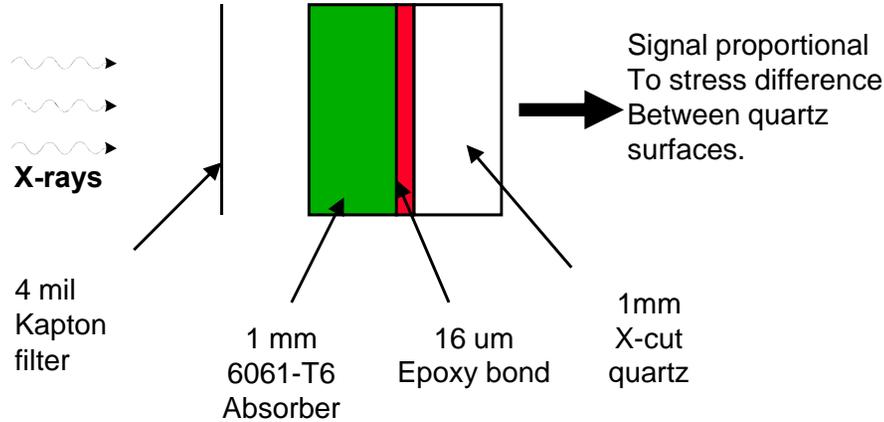
UQ for Validation: Presto Simulations vs. Z-Accelerator Data



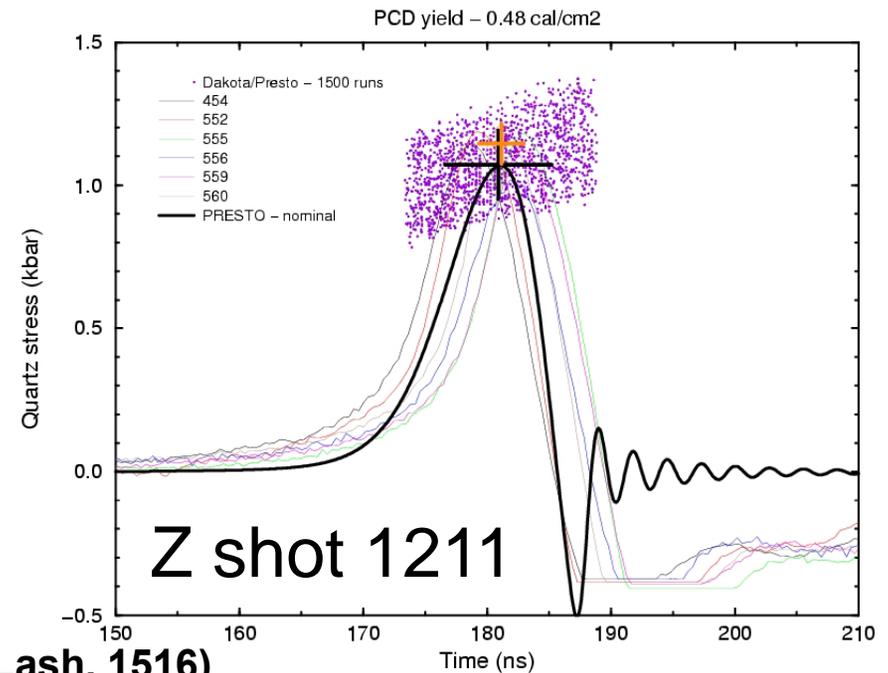
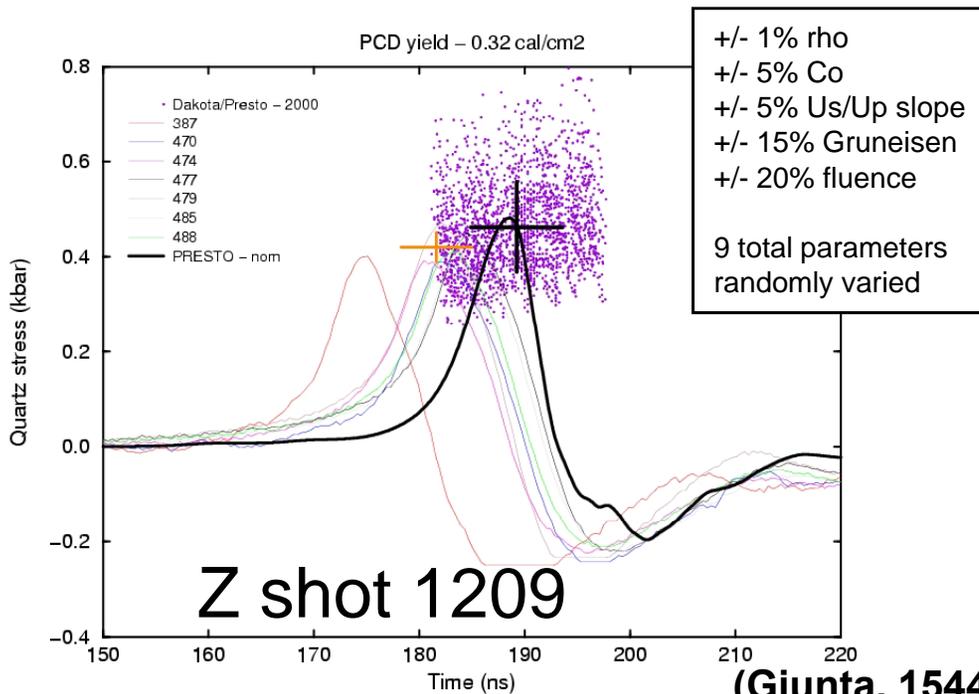
Tungsten wire array & Z pinch



X-Ray Induced Thermomechanical Shock Modeled w/ Presto



- UQ study on Presto thermomechanical shock
- DAKOTA+Presto, 2000 runs; on distributed network of workstations
- Compared Presto vs. Z Shot $\mu \pm 1\sigma$ uncertainty
- UQ study gave info on design margins; identified need for model improvement





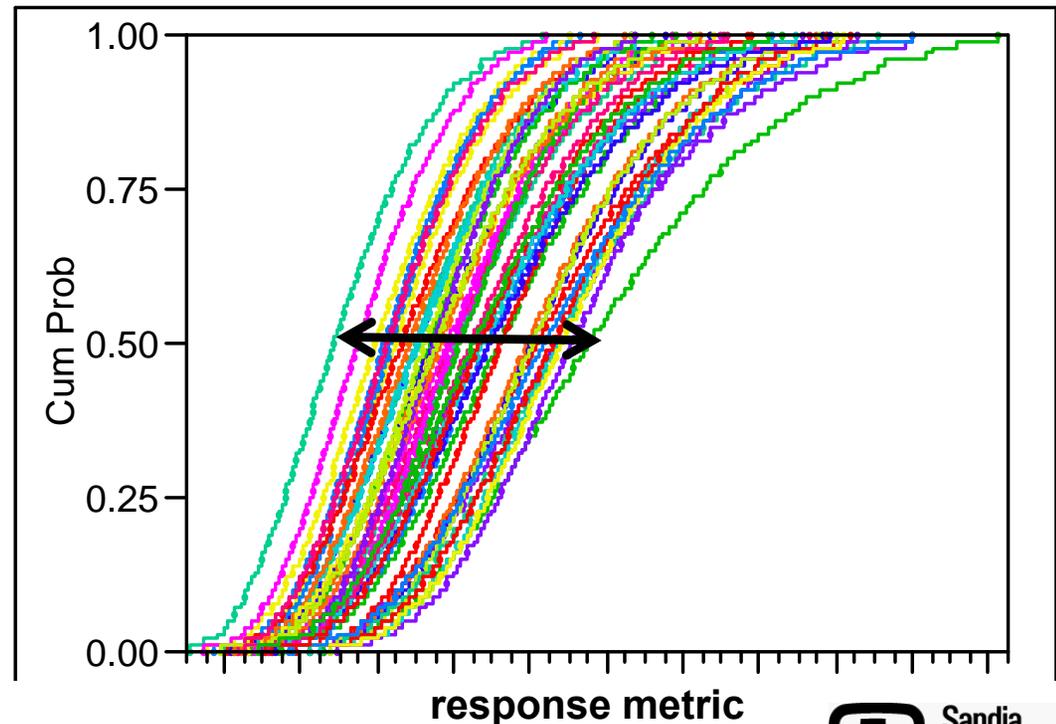
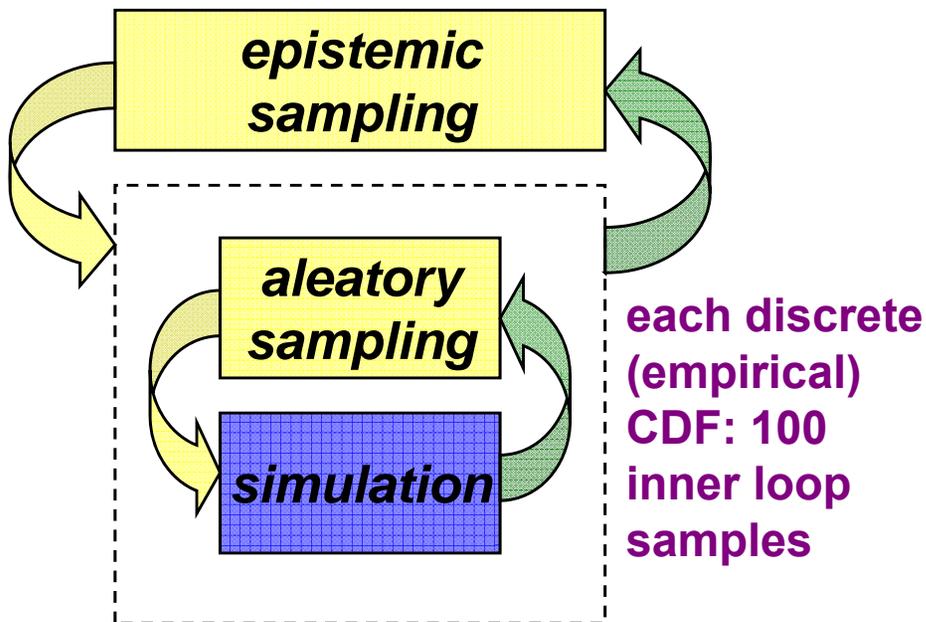
- Techniques for propagating **aleatory uncertainty** (variables characterized by probability distributions) through models:
 - Latin hypercube (and other) sampling
 - Local reliability methods (mean value, MPP search, FORM, SORM)
 - Global reliability methods (EGRA)
 - Non-intrusive stochastic expansion methods (polynomial chaos and stochastic collocation)
- Methods for **epistemic uncertainty** (variables characterized by intervals or basic probability assignments):
 - Local/global interval estimation
 - Local/global Dempster-Shafer evidence theory (belief/plausibility)
 - “Second-order” probability
- **DAKOTA can output probability of response thresholds, reliability metrics, response corresponding to a metric, etc.**

“Second-Order” Probability



- Nested sampling technique frequently used in QMU studies
- For each outer loop sample of epistemic (interval) variables, run an inner loop UQ study over aleatory (probability) variables
- **Example: Radiation Transport milestone studies:** Uncertainties in materials, energies, incoming radiation characteristics → determine uncertainty range on output measures like current or voltage and if requirements met

50 outer loop samples
→ 50 CDF traces

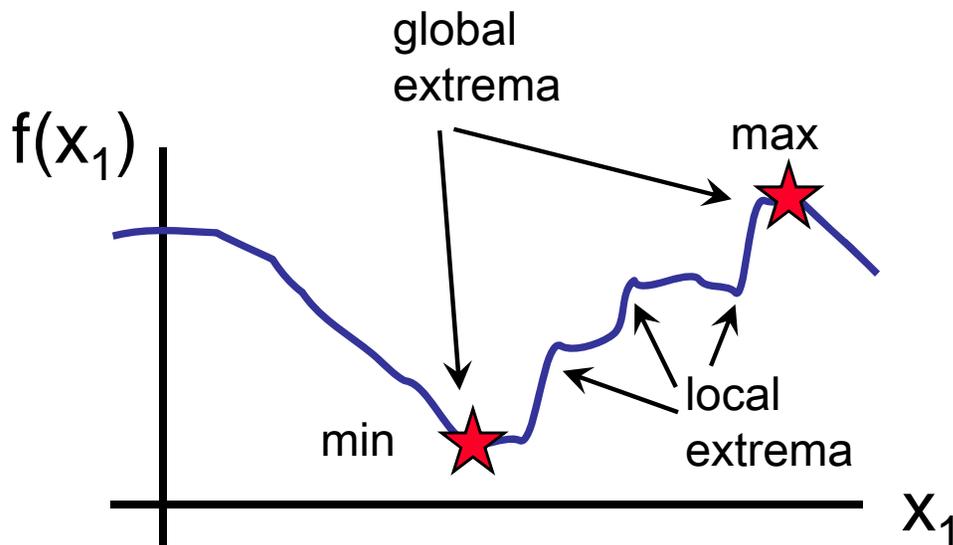


“Envelope” of CDF traces represents response epistemic uncertainty

Optimization

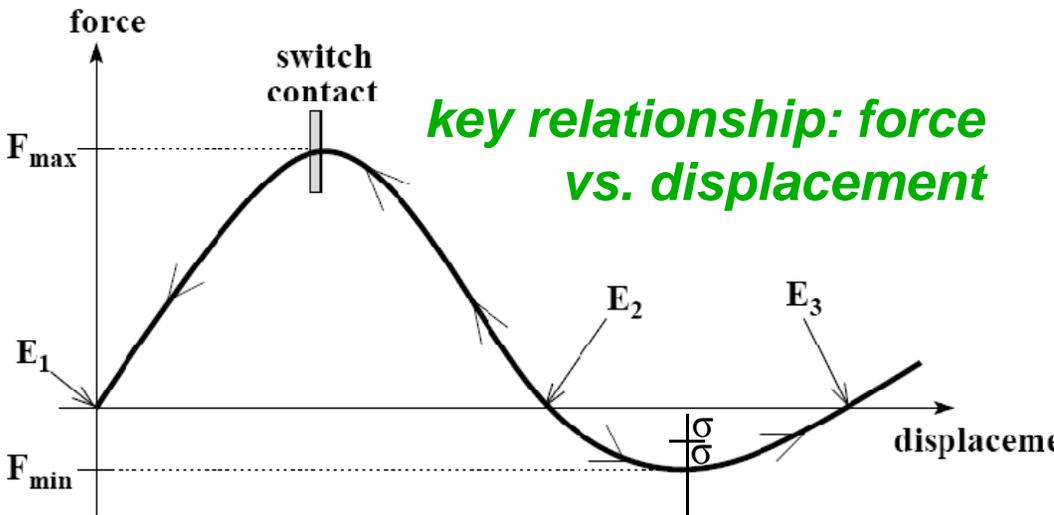
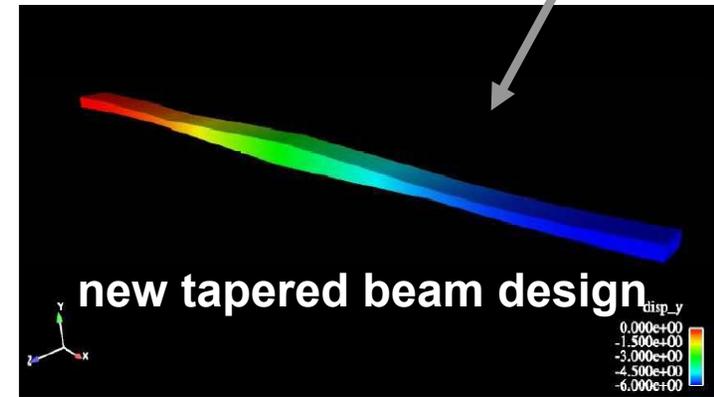
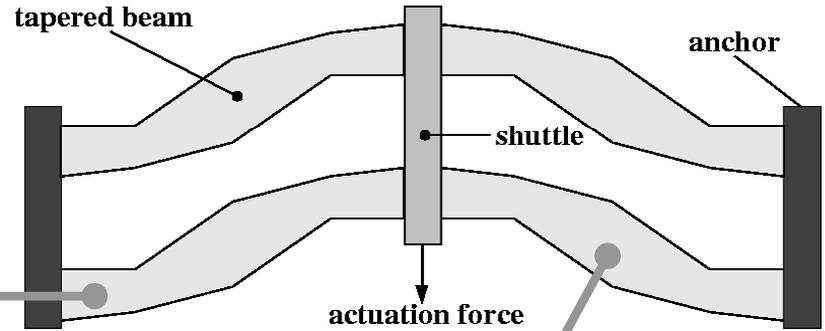
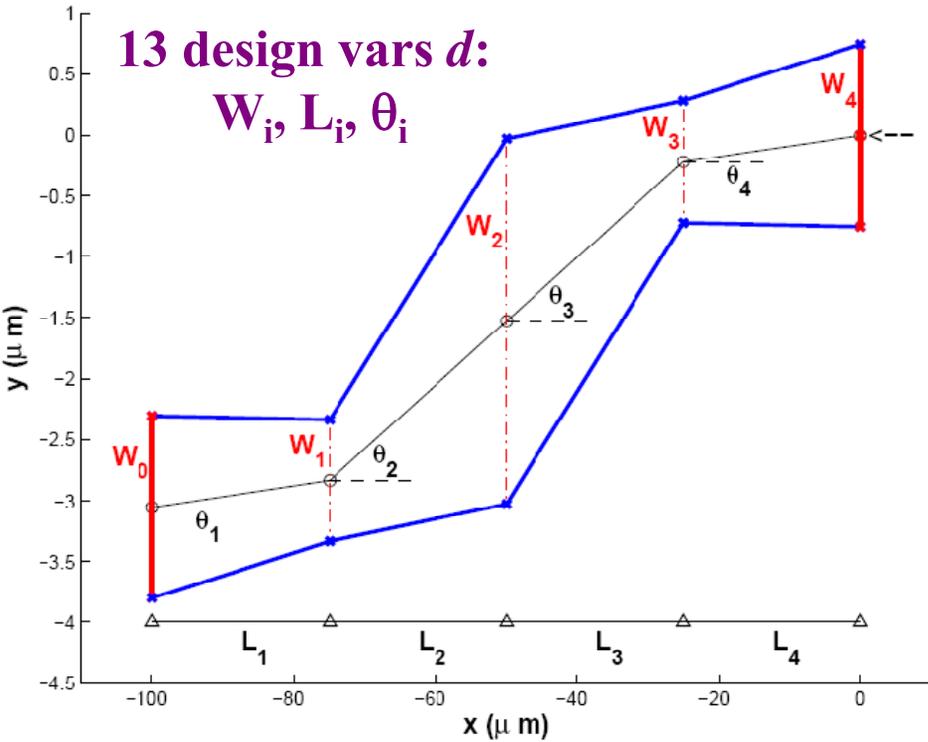


- **GOAL: Vary parameters to extremize objectives, while satisfying constraints to find (or tune) the best design, estimate best parameters, analyze worst-case surety, e.g., determine:**
 - delivery network that maximizes profit while minimizing environmental impact
 - case geometry that minimizes drag and weight, yet is sufficiently strong and safe
 - material atomic configuration of minimum energy



Some applications: local improvement suffices; others: must find global minimum at any cost

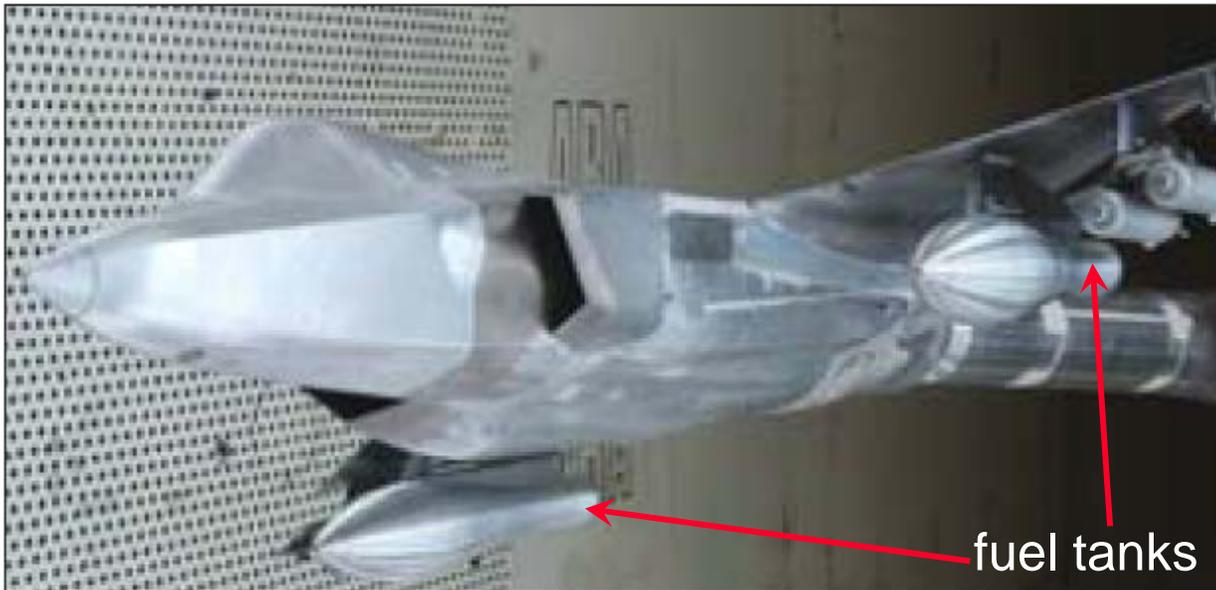
MEMS Switch Design: Geometry Optimization



Typical design specifications:

- actuation force F_{\min} reliably 5 μN
- bistable ($F_{\max} > 0, F_{\min} < 0$)
- maximum force: $50 < F_{\max} < 150$
- equilibrium $E2 < 8 \mu\text{m}$
- maximum stress $< 1200 \text{ MPa}$

Optimization for Lockheed-Martin F-35 External Fuel Tank Design



This wind tunnel model of F-35 features an optimized external fuel tank.

F-35: stealth and supersonic cruise

~ \$20 billion cost

~ 2600 aircraft (USN, USAF, USMC, UK & other foreign buyers)

LM CFD code:

- **Expensive: 8 hrs/job on 16 processors**
- **Fluid flow around tank highly sensitive to shape changes**

“Lockheed Martin Aeronautics conducted a trade study for the F-35 Joint Strike Fighter (JSF) aircraft to design the external fuel tank for improved performance, store separation, and flutter. **CFD was used in conjunction with Sandia National Laboratories’ Dakota optimization code to determine the optimal shape of the tank that minimizes drag for maximum range and minimizes yawing moment for separation of adjacent stores.** Data obtained at several wind tunnel facilities verified the predicted performance of the new aeroshaped, compartmented tank for separation and flutter, as well as acceptable characteristics for loads, stability, and control.” -- Dec. 2004 *Aerospace America*, p. 22

DAKOTA Optimization Methods



Gradient-based methods

(DAKOTA will compute finite difference gradients and FD/quasi-Hessians if necessary)

- *DOT (various constrained)*
- CONMIN (FRCG, MFD)
- NPSOL (SQP)
- NLPQL (SQP)
- OPT++ (CG, Newton)

Calibration (least-squares)

- NL2SOL (GN + QH)
- NLSSOL (SQP)
- OPT++ (Gauss-Newton)

Derivative-free methods

- COLINY (PS, APPS, Solis-Wets, COBYLA2, EAs, DIRECT)
- JEGA (single/multi-obj GAs)
- EGO (efficient global opt via Gaussian Process models)
- DIRECT (Gablonsky)
- OPT++ (parallel direct search)

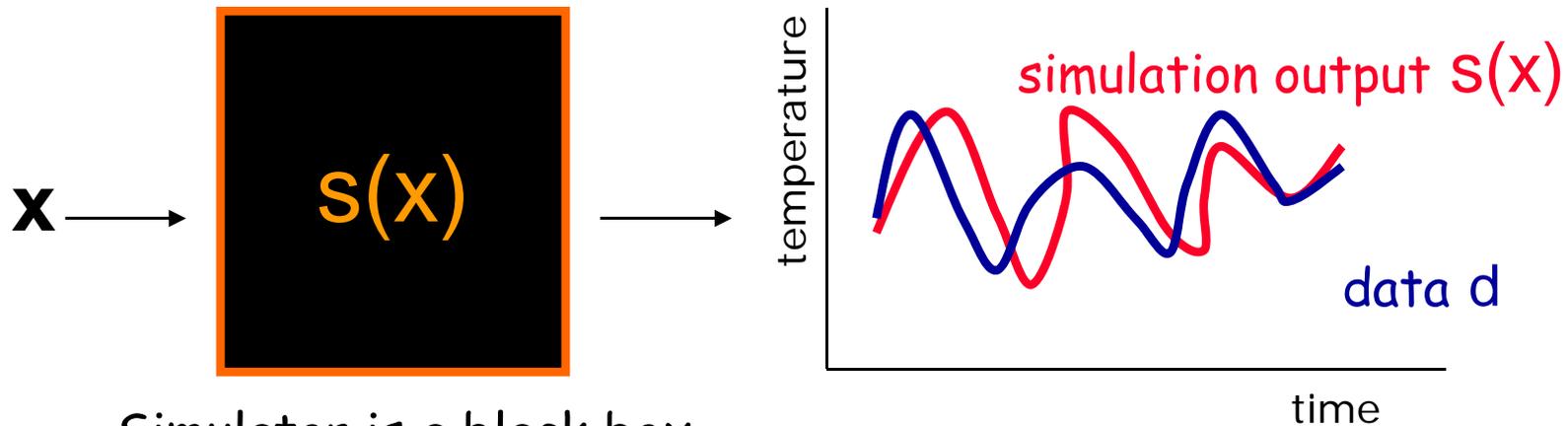
- *TMF (templated meta-heuristics framework)*

Calibration/Parameter Estimation



$$f(x) = \sum_{i=1}^n \underbrace{(s_i(x))}_{\text{Simulation output that depends on } x} - \underbrace{d_i}_{\text{Given data}})^2$$

Simulation output that depends on x Given data



Simulator is a black box

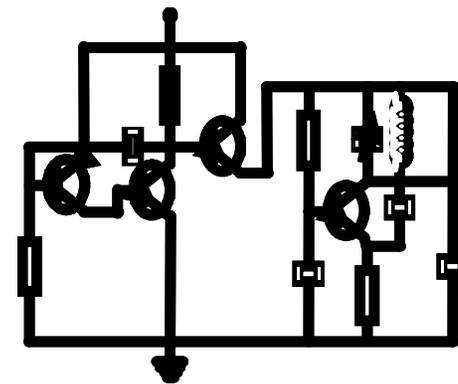
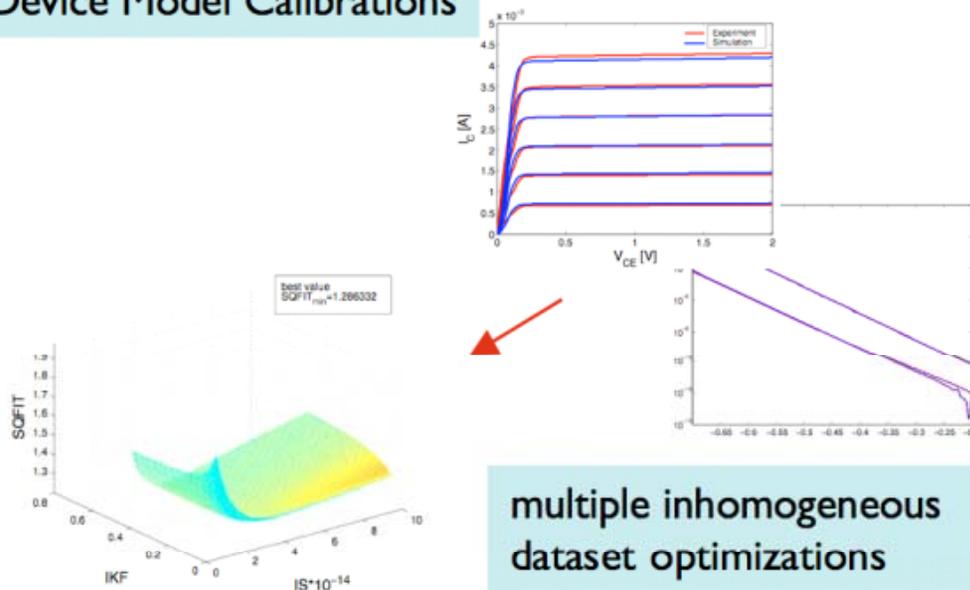
Calibration: Adjust model parameters (x) to maximize agreement with a set of experimental data (AKA parameter estimation, parameter identification, systems, identification, nonlinear least-squares)

QASPR Model Calibration



- **QASPR Model Calibration:** develop defensible predictive models to replace physical testing with fast neutrons
- Use experimental data to calibrate Complex Prototype Model in Xyce, understand limitations and effects of uncertainty
- HPC runs for parameter screening, determining nominal parameters via calibration, assessing robustness of optima

Device Model Calibrations





DAKOTA Overview Goals



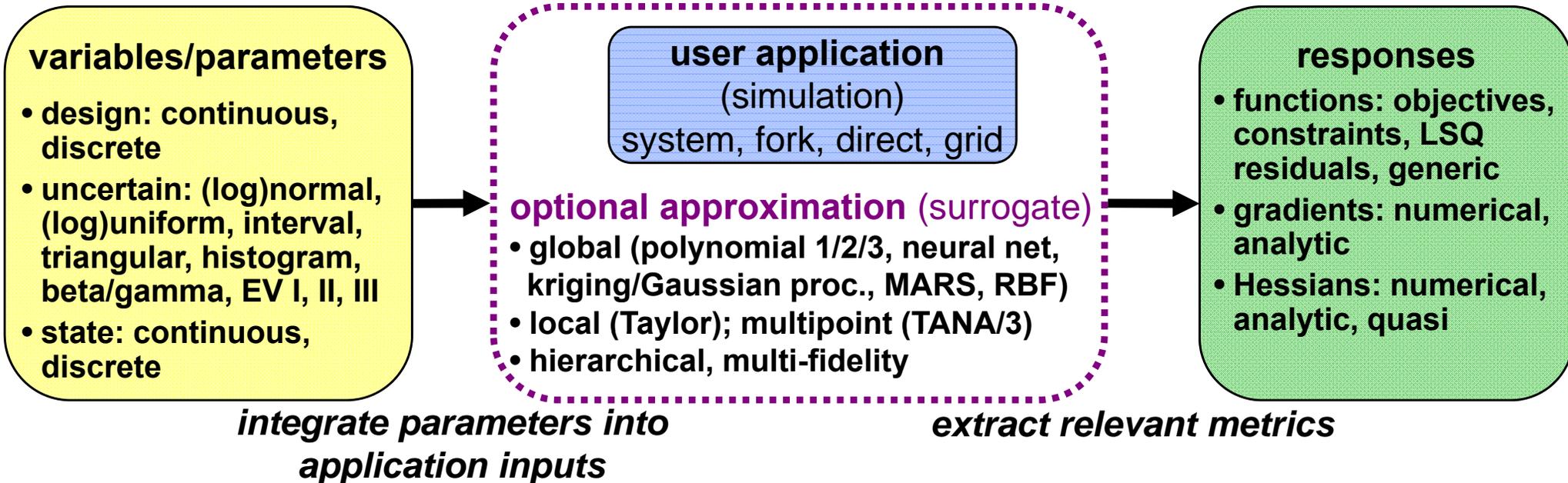
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Flexibility with Models



DAKOTA models map inputs to response metrics of interest:



Flexible interface to user application (computational model/simulation)

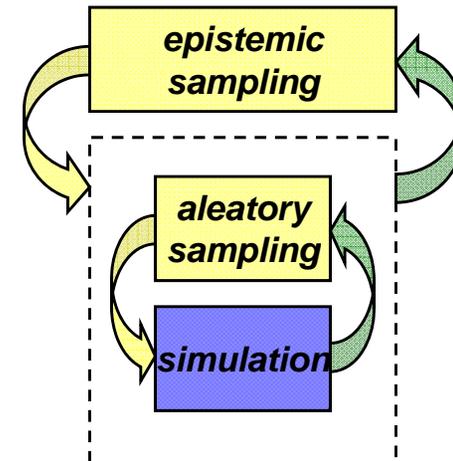
- May be cheap (analytic function, linear analysis); **typically costly** (finite element mesh with millions of DOF, transient analysis of integrated circuit with millions of transistors)
- Built-in response surfaces/meta-models/surrogates improve efficiency
- May run tightly-coupled, locally as separate process, in parallel on a cluster, remotely on a distributed resource

Strategies (and advanced/multi-component methods)



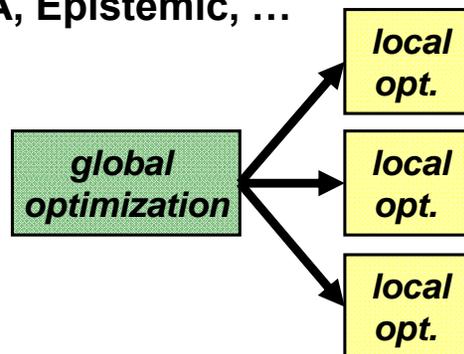
Strategies (general nesting, layering, sequencing and recasting facilities) **combine methods to enable advanced studies:**

- opt within opt (multilevel opt & hierarchical MDO)
 - UQ within UQ (second-order probability)
 - UQ within opt (OUU) and NLS (MCUU)
 - opt within UQ (uncertainty of optima)
- with and without surrogate model indirection*



Optimization

- Surrogate-based: data fit, multifidelity, ROM
- Mixed integer nonlinear programming (MINLP): PEBBL (parallel branch and bound)
- Optimization under uncertainty
 - TR-SBOUU, RBDO (Bi-level, Sequential)
 - MCUU, PC-BDO, EGO/EGRA, Epistemic, ...
- Hybrids (e.g., global/local)
- Pareto set
- Multi-start
- Multilevel methods



Uncertainty

- Second order probability
- Uncertainty of optima

Nonlinear least squares

- Surrogate-based calibration
- Model calibration under uncertainty

Scalable Parallelism

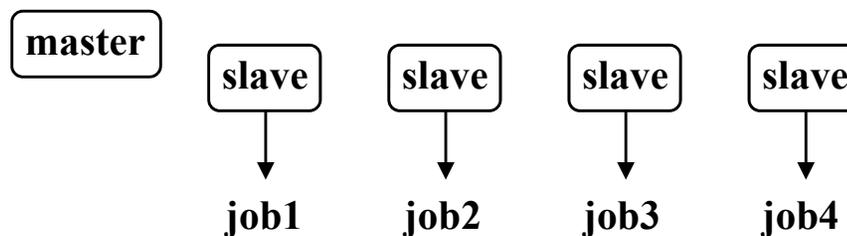


Nested parallel models support large-scale applications and architectures.

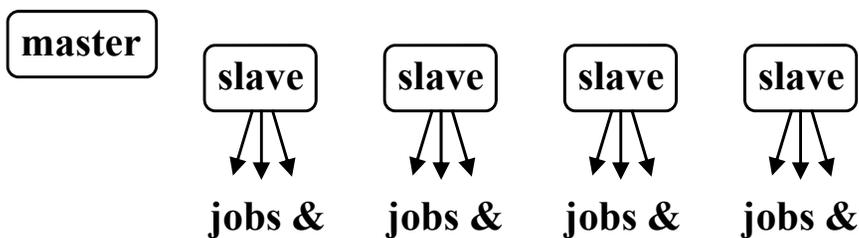
1. SMP/multiprocessor workstations: Asynchronous (external job allocation)



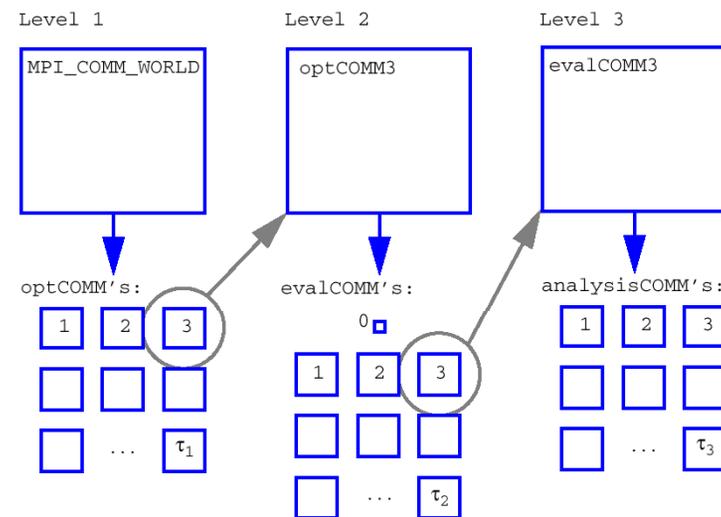
2. Cluster of workstations: Message-passing (internal job allocation)



3. Cluster of SMP's: Hybrid (service/compute model)



4. MPP (Red Storm/White): Internal MPI partitions (nested parallelism)



Input File for Parameter Study



```
## DAKOTA INPUT FILE - dakota_rosenbrock_2d.in

strategy
  single_method
  graphics tabular_graphics_data

method
  multidim_parameter_study
  partitions = 8 8

model
  single

variables
  continuous_design = 2

  lower_bounds      -2.0      -2.0
  upper_bounds      2.0       2.0
  descriptors       'x1'      "x2"

interface
  direct
  analysis_driver = 'rosenbrock'

responses
  num_objective_functions = 1
  no_gradients
  no_hessians
```



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DAKOTA 5.0 Highlights



- GNU Lesser General Public License (enables library use of DAKOTA)
- All new JAGUAR 2.0 graphical user interface for creating, editing, and running DAKOTA input files (BSD-like license)
- **DAKOTA modules on SNL compute clusters (module avail dakota)**
- Creation and management of evaluation working directories
- Parallelism examples; pre/post run; Mac / Windows binaries
- Additional discrete variable types; supported by parameter studies, nondeterministic sampling (discrete distributions), JEGA, and COLINY
- Stochastic expansion: Anisotropic sparse grids, numerically-generated orthogonal polynomials, and improved expansion tailoring; *many more not detailed here!*
- New epistemic and mixed aleatory-epistemic UQ: local/global interval estimation and local/global evidence.



Getting Started with DAKOTA



- Access a Sandia installation (preferred)
AMECH (CA), CEE (ESHPC/SCICO, NM), Computer clusters (both)
or download (Analyst Home Page or DAKOTA webpage)
- Supported on Linux, Solaris, AIX (purple), Mac OS X, Windows (no MinGW or Cygwin install required), Redstorm
- Attend a DAKOTA training class
- User's Manual, Chapter 2: Tutorial, corresponding examples distributed with DAKOTA
- Support:
 - dakota-users@software.sandia.gov
(DAKOTA team and internal/external user community)
 - dakota-developers@development.sandia.gov
(for issues involving proprietary information)



DAKOTA Training Classes



New modular format:

- **DAKOTA 101 (intro to using DAKOTA)**
half day, interactive lecture, optional hands-on (laptop)
- **Interface DAKOTA to your application**
half day, hands-on small group workshop
- **Advanced topics in DAKOTA User's Group Meetings**
- **Method theory and selection (2 hours each):**
 - **Sensitivity analysis / screening**
 - **Optimization and calibration**
 - **Uncertainty quantification**

JAGUAR 2.0



- All new graphical user interface for creating, editing, and running DAKOTA input files
- Lead: Ethan Chan (8964), supported by DART and DAKOTA teams
- Java; based on Eclipse IDE/Workbench
- Windows, Mac, Linux support



- Synchronized text and hierarchical graphical editors
- Templates for common studies
- Error checking and integrated help
- Sensitivity analysis wizard

JAGUAR Graphical Editor



The screenshot displays the Jaguar graphical editor interface. The title bar reads "Jaguar - DART Workspace/Documents and Settings/briadam/My Documents/dakota/DART_GUI/testing/LHSscreening.i - Jaguar". The menu bar includes "File", "Edit", "Navigate", "Window", and "Help". The main window is titled "LHSscreening.i" and shows a "Define Flow/Iteration" configuration panel.

Sections: A tree view on the left shows the project structure: STRATEGY, METHOD, Method, Nondeterministic sampling method, and Sampling type.

Nondeterministic sampling method: This section is active and contains the following configuration options:

- Sampling type:** Checked. Includes a details field with "lhs *".
- Variance based decomposition:** Unchecked.
- Random seed for stochastic pattern search:** Checked. Value: 12345.
- Number of samples:** Checked. Value: 150.
- Distribution type:** Unchecked.
- Probability levels:** Unchecked. Value: Optional Array of reals. Default value: 0,0. Counter: 0.
- Generalized reliability levels:** Unchecked. Value: Optional Array of reals. Default value: 0,0. Counter: 0.
- Random seed generator:** Unchecked.
- Reliability levels:** Unchecked. Value: Optional Array of reals. Default value: 0,0. Counter: 0.
- Response levels:** Unchecked. Value: Optional Array of reals. Default value: 0,0. Counter: 0.
- All variables flag:** Unchecked.
- Fixed seed flag:** Unchecked.

The bottom status bar shows a progress indicator with four steps: 1 Define Problem, 2 Define Flow/Iteration (current), 3 Execute Problem, and 4 Visualize Results.

JAGUAR Text Editor



```
1 method
2  nond_sampling
3  sample_type
4  lhs
5  samples = 150
6  seed = 12345
7
8 variables
9  uniform_uncertain = 3
10 lower_bounds = -0.5 10 400
11 upper_bounds = 0.5 20 600
12 descriptors = 'xdeviation' 'ydeviation' 'mass'
13
14 interface
15 analysis_drivers = 'text_book'
16 direct
17
18 responses
19 num_response_functions = 2
20 no_gradients
21 no_hessians
22
```

JAGUAR Sensitivity Analysis Wizard



DAKOTA Sensitivity Analysis Wizard (Pre-run)

Specify Variables

Specify the table contents

Uniform Uncertainty

Number of samples: 150

uniform uncertain variables: 3

Descriptors	Distribution lower bounds*	Distribution upper bounds*
'xdeviation'	-0.5	0.5
'ydeviation'	10	20
'mass'	400	600

Number of response functions: 2

Generate samples
 Save input file:



JAGUAR Plans

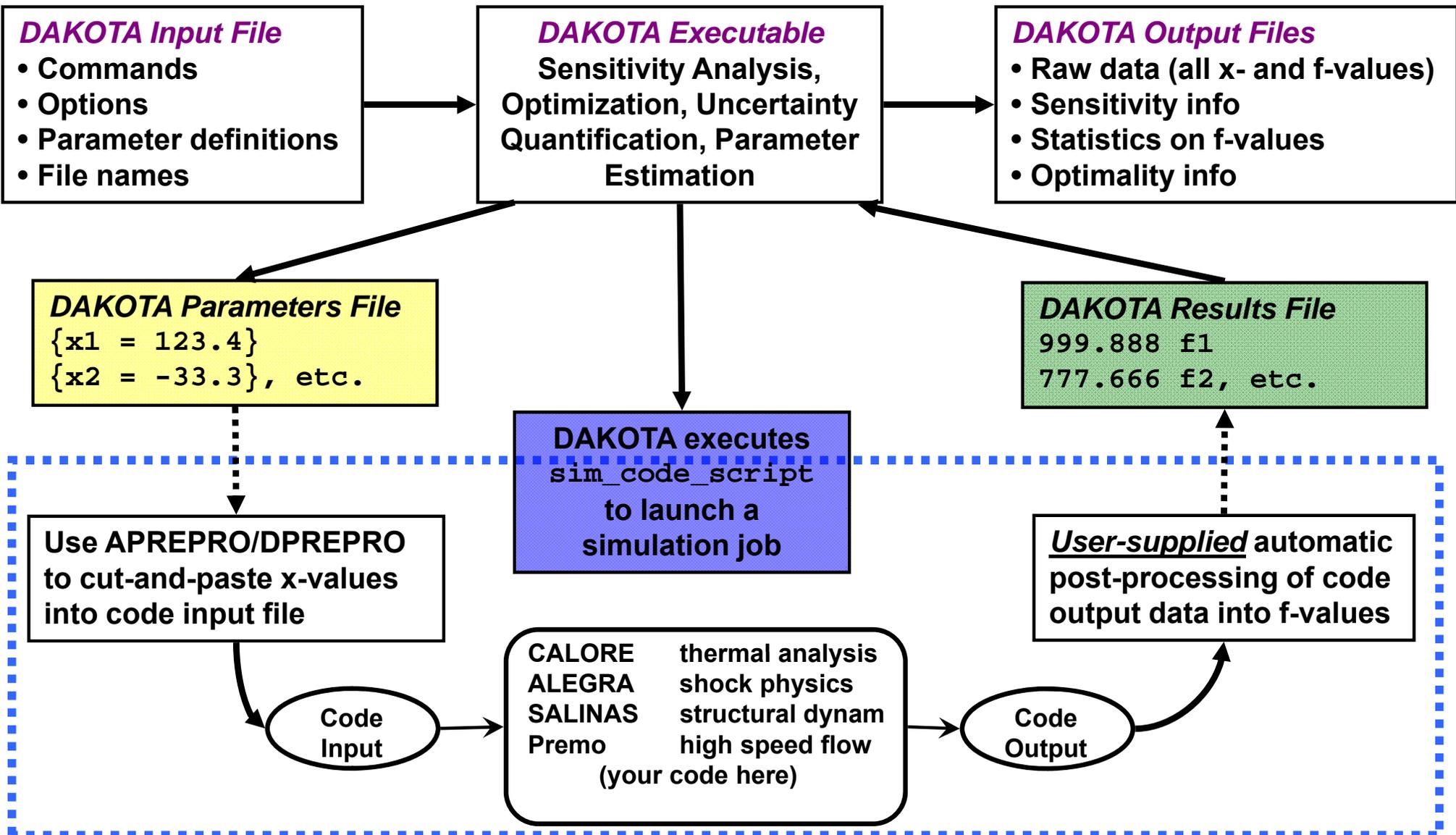


-
- Remote job submission to compute clusters
 - Integration with DART Workbench
 - Better help facilities
 - Usability enhancements
 - Wizards for creating various kinds of studies

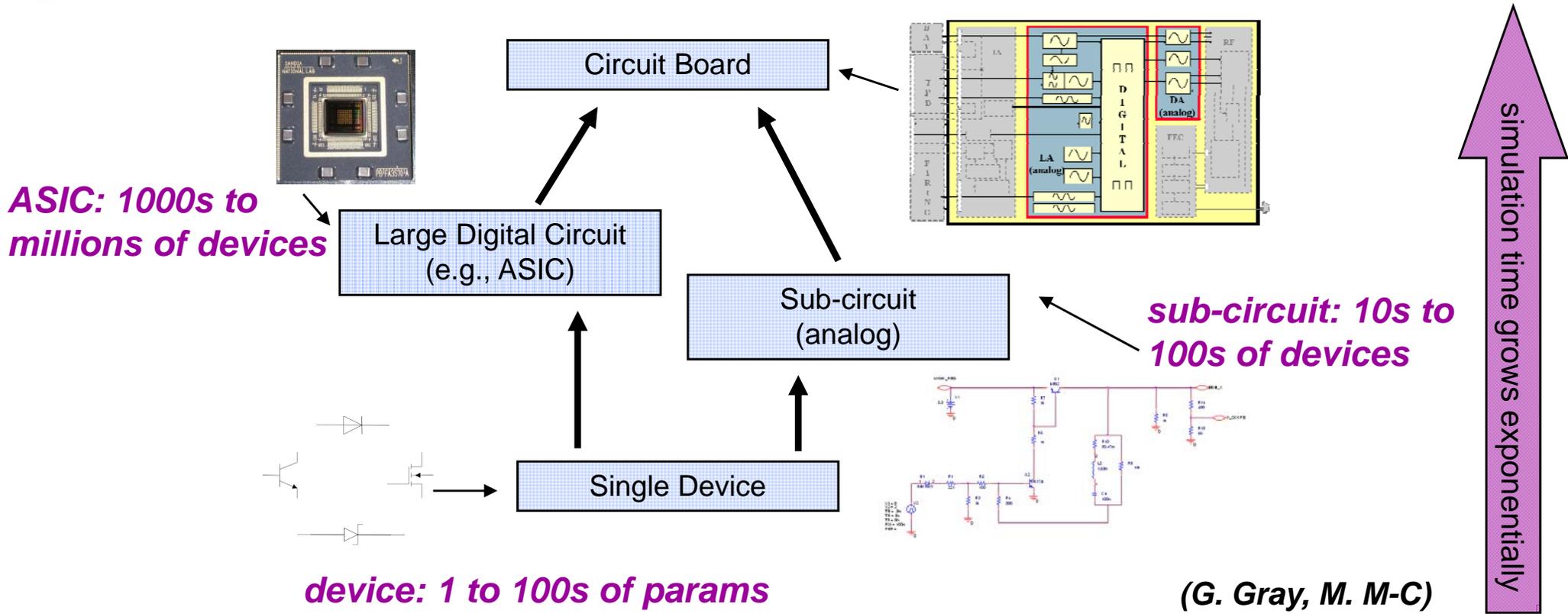


Bonus Slides

DAKOTA Execution & Info Flow



Electrical Modeling Complexity



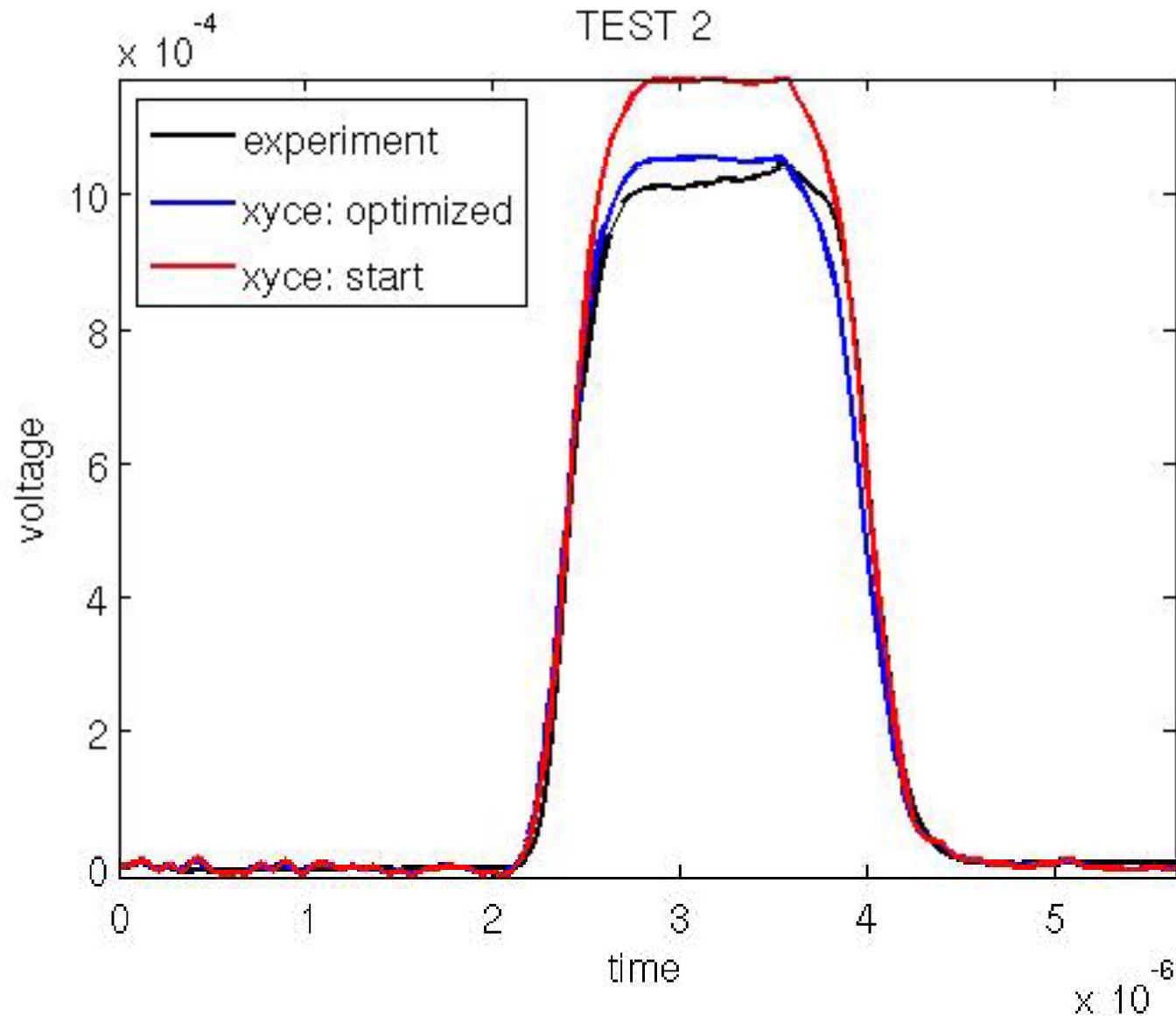
- **simple devices:** 1 parameter, typically physical and measurable
- e.g., resistor @ $100\Omega \pm 1\%$
- resistors, capacitors, inductors, voltage sources

- **complex devices:** many parameters, some physical, others “extracted” (calibrated)
- multiple modes of operation
- e.g., zener diode: 30 parameters, 3 bias states; many transistor models (forward, reverse, breakdown modes)

Sample Signal Calibration



- Calibration of 8 circuit parameters to match experimental signal (G. Gray, M. M-C)

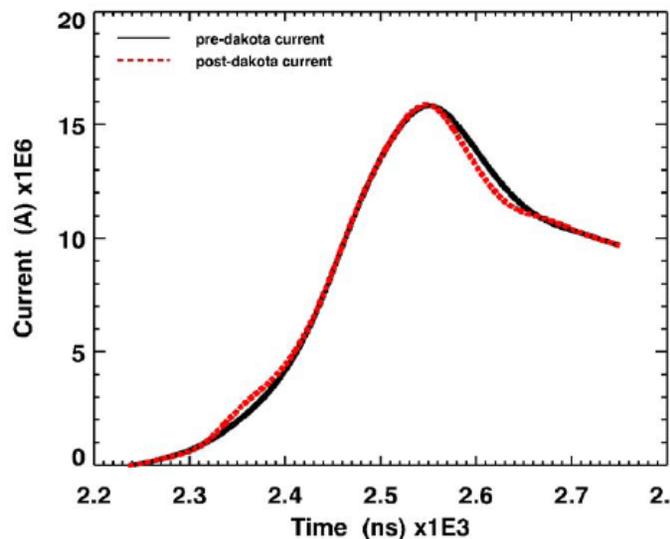


DAKOTA Calibration Study: ALEGRA Simulations vs. Z-Accelerator Data

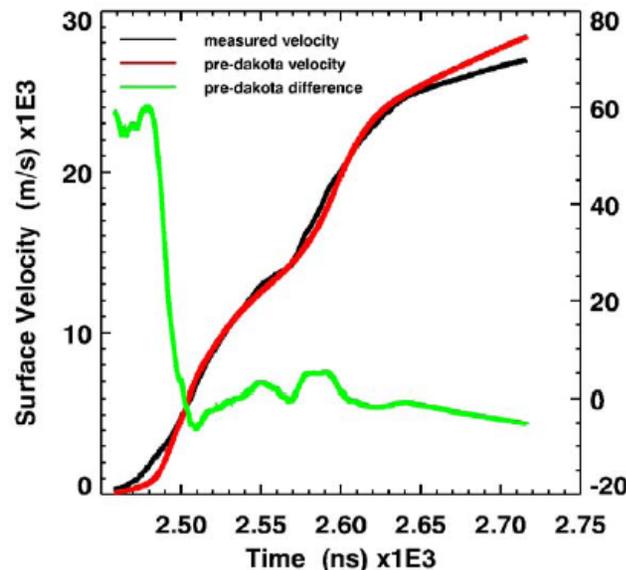


- **Goal:**
 - Isentropically compress materials and/or shocklessly accelerate flyers to high velocity (~30 km/s) for equation-of-state (EOS) measurements.
 - Increased accuracy in EOS data impacts both NW and inertial confinement fusion applications.
- **Approach:**
 - Current-vs.-time conditions during Z shot not measured with sufficient accuracy for use in ALEGRA simulations.
 - Flyer plate velocity is measured with sufficient accuracy.
 - Solution - DAKOTA optimizes the current waveform (left) to match ALEGRA velocity data to Z velocity data.
- **Results:**
 - Optimized velocity (right) more accurate than initial velocity (center): 17% vs. 24% max error
 - The optimized current waveform (left) permits high-fidelity ALEGRA magneto-hydrodynamic simulations.
 - Waveform for shot Z1446 was tuned to eliminate shock formation during compression [shocks preclude getting EOS data].
 - Z1446 post-shot data analysis showed no shock formation in material sample – good EOS data.
 - Future studies: optimize current shapes for Z and ZR shots; uncertainty quantification for Z and ZR shots.
- **Contacts:**
 - DAKOTA - Tony Giunta, Dept. 9133, aagiunt@sandia.gov, 505/844-4280
 - Z & ALEGRA – Ray Lemke, Dept. 1674, rwlemke@sandia.gov, 505/845-7423

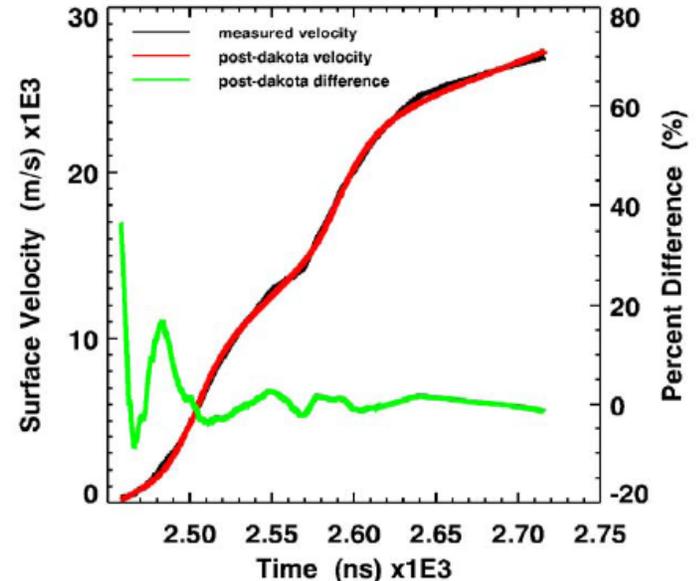
initial and final currents



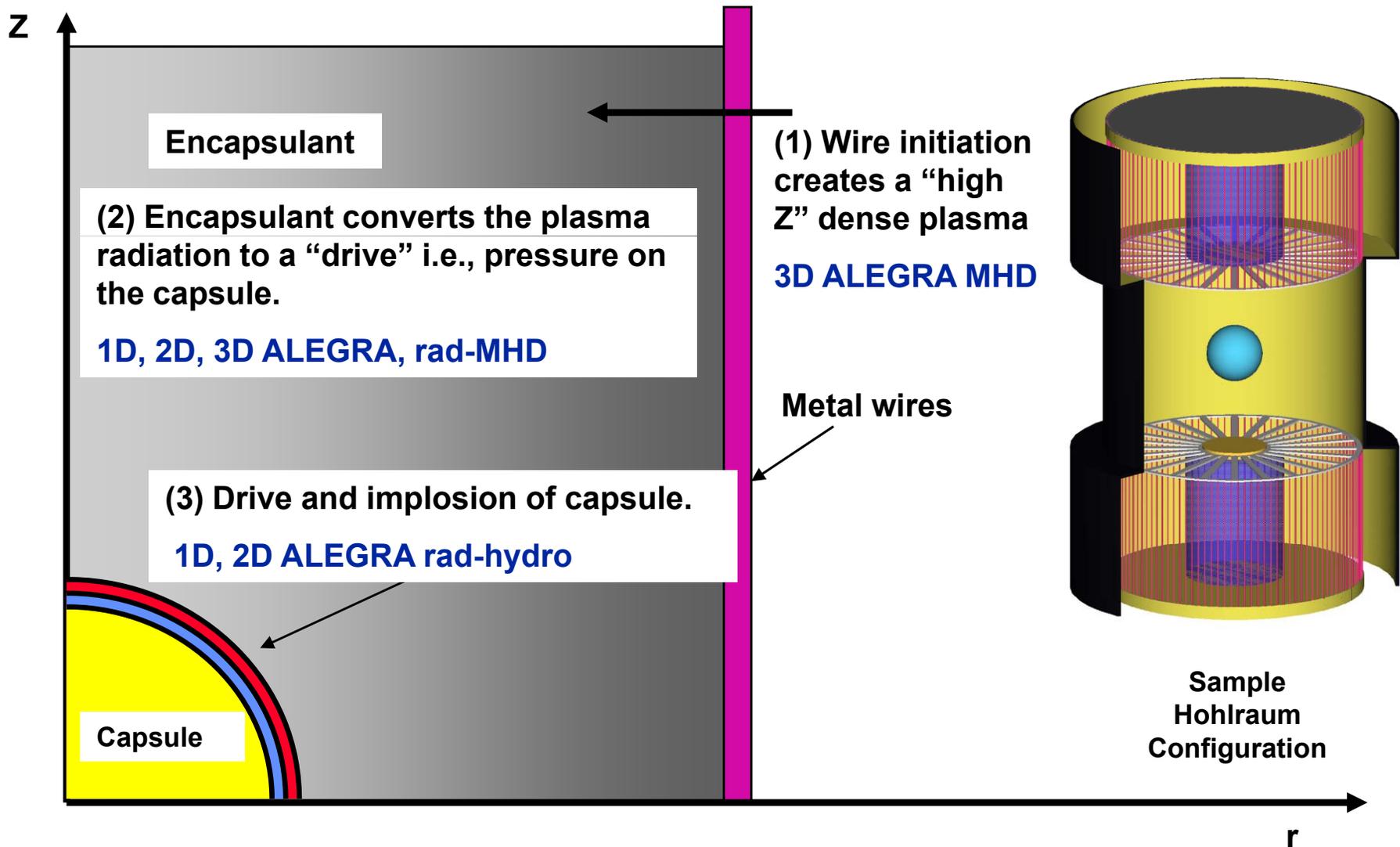
initial and measured flyer velocities



final and measured flyer velocities



Robust Hohraum Design for Inertial Confinement Fusion

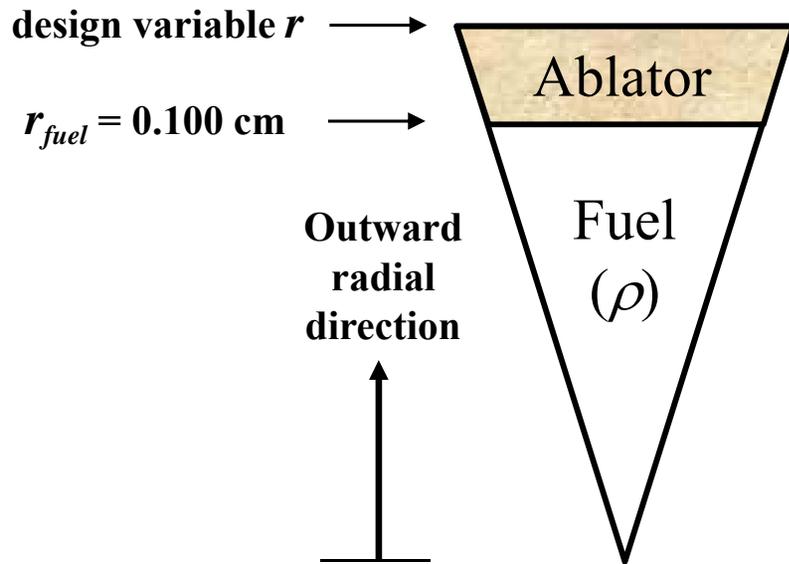


Uncertainties in plasma, drive, and capsule characteristics

ICF Capsule Robust Design



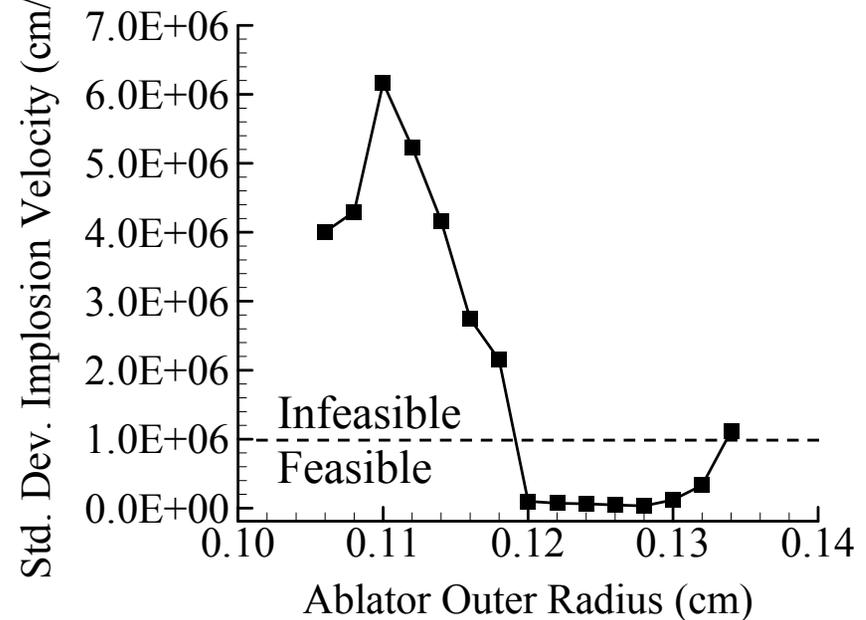
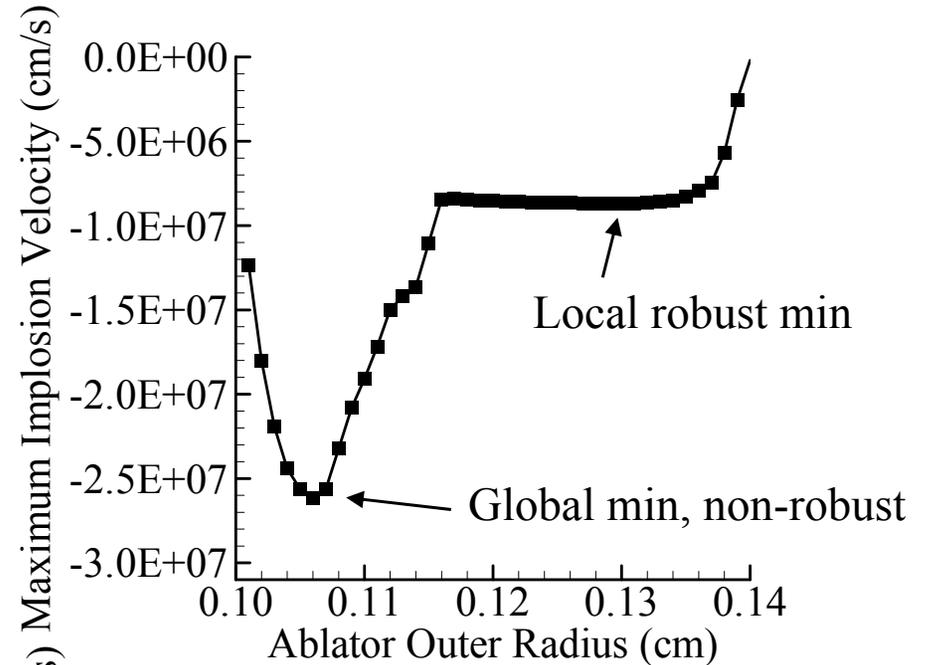
Design goal: **maximize the implosion velocity** w.r.t. ablator radius r and fuel density ρ , but remain **robust** w.r.t. manufacturing variability



Minimize $V(r, \rho)$

Subject to $\sigma_V(r, \rho) \leq \text{target value}$

uniform: $\pm 2.5\%$ range in r, ρ



New Capability in DAKOTA 5.0



Usability / core execution

- JAGUAR 2.0 graphical user interface, based on Eclipse Workbench, with text- and graphical-based editing, templates, sensitivity analysis wizard, and error checking. Available via separate download after registering for DAKOTA download.
- Capability to specify working directories, template directories, and lightweight linking for system and fork interfaces.
- DAKOTA input files can use Matlab-style sequence notation (L:S:U and beyond) to specify variable ranges; improved tolerance for whitespace in input files
- Improved DAKOTA + application parallelism examples; new asynchronous local evaluation static scheduling for improved parallel tiling on clusters.
- Pre-run (with optional variables output) and post-run (with variables/responses input) modes supported by sampling, parameter study, and DACE methods
- Examples of Matlab and Python interfaces
- Automated cleanup of DAKOTA temporary files on unexpected exit

Variables

- Refactor of **Variables** and **Constraints** hierarchies to manage continuous, discrete integer, and discrete real domains among design, aleatory uncertain, epistemic uncertain, and state types.
 - Additional discrete design variable types: discrete design integer range, discrete design integer set, discrete design real set
 - New discrete uncertain distributions: poisson, binomial, negative binomial, geometric, hypergeometric
 - Additional discrete state variable types: discrete state integer range, discrete state integer set, discrete state real set
- Updates to specification of continuous and discrete histograms
- Alternate specification for lognormal using lambdas and zetas

New Capability in DAKOTA 5.0



Methods (general)

- New capability to perform parameter studies and sampling over discrete variables. New discrete variable types also supported in JEGA and COLINY.
- DACE and parameter study classes (DDACE, FSUDACE, and multi-dimensional parameter study) can have correlations calculated and printed in addition to sampling methods
- Improved accuracy and robustness in correlation computations
- PSUADE: use updated (Campolongo 2007) sample generation scheme to improve space-filling properties
- Improved EGO convergence controls (based on nearest neighbor)
- Beta capabilities:
 - wrapper class for LANL's GPMSA code (Bayesian calibration)
 - importance sampling capability
 - nonlinear conjugate gradient optimization solver using Trilinos vector-matrix utilities
- Bug fixes:
 - hang in DDACE orthogonal array LHS
 - OPT++ NIP methods not respecting bound constraints
- New example problems for multifidelity OUU (MVFOSM as low fidelity UQ and stochastic expansion as high fidelity UQ), epistemic UQ, mixed aleatory-epistemic UQ, discrete sampling and parameter studies, etc.

New UQ in DAKOTA 5.0



- Stochastic expansions (polynomial chaos expansion (PCE) and stochastic collocation (SC)):
 - Simplified controls for PCE: expansion formulation now inferred or estimated from `quadrature_order` or `sparse_grid_level` specifications. Automatic expansion tailoring minimizes performance loss due to poor expansion/integration synchronization.
 - Addition of numerically-generated orthogonal polynomials for generating optimal basis for non-Askey distribution types (uses Gauss-Wigert or discretized Stieltjes procedures for polynomial recursion coefficients in combination with Golub-Welsch for Gauss point/weight computation)
 - Addition of analytic variance-based decomposition for global sensitivity analysis using method of Sobol indices
 - Addition of analytic covariance among multiple response functions.
 - Addition of anisotropic Smolyak sparse grids, with user-supplied dimension preference.
 - Revision of Gaussian quadrature rules within sparse grids to use linear growth, providing finer grain control and more uniform integrand coverage.
 - PCE customizations for sparse grids: exclusive usage of linear growth rules (no Clenshaw-Curtis or Gauss-Patterson), total-order expansions for isotropic, custom expansion for anisotropic.
 - Addition of Askey and Wiener basis polynomial over-rides.
 - Modified variable correlation logic to revert to Wiener expansions for de-correlation as needed on a per-variable basis.
 - `all_variables` mode now includes epistemic uncertain variables (previously design and state only) using a Legendre basis.
- Epistemic UQ methods:
 - Refactor of **NonDInterval** hierarchy to generalize and incorporate new methods.
 - Evidence: new global (LHS or EGO) and local (SQP or NIP) methods to calculate belief and plausibility in evidence theory calculations. Removed dependence on legacy Fortran package.
 - Interval estimation: new global (LHS or EGO) and local (SQP or NIP) methods to calculate response output intervals.
 - Extension of active Variables/Constraints views to support aleatory, epistemic, or aggregated aleatory-epistemic uncertain views.
- Mixed aleatory-epistemic UQ methods:
 - New nested approaches (e.g. second-order probability, mixed evidence) where the outer loop (e.g. interval estimation or evidence) can leverage analytic moments and their sensitivities with respect to epistemic parameters.

New Capability in DAKOTA 5.0



Framework Enhancements

- Eliminated dependence on GSL in favor of Boost (to eliminate GNU GPL dependency)
- Fully deployed Teuchos for all numerical data types. Boost and STL are used for all bookkeeping types.
- Better out-of-source (VPATH) builds and documentation, including management of Boost and Teuchos
- Switched from RNUM2 to Boost MT19937 random number generator for longer period, with run-time selection option
- Deployed [Boost multi-index](#) containers to evaluation queue management, supporting multiple indexing options for optimized lookups.
- Lightweight active/inactive data views implemented with Teuchos and [Boost multi-array](#) to eliminate deep data copies.
- Updates to third-party libraries: JEGA, PSUADE, AMPL, Boost, Pecos, Teuchos
- Minimal data mode for variables and responses omits labels, types, ids in some contexts for better scalability
- Unified bounds checking for debugging and reduced overhead in optimized builds

Miscellaneous

- Binary distributions for Mac OS X and Cygwin, including library dependencies
- Better detection of MPICH2 and shmexec communicators
- Automatic synchronization of DAKOTA input specification help docs to JAGUAR
- Surfpack: improved random seed management for repeatability.
- Better handling of numerical comparisons on 32-bit
- Finite differencing honors variable bounds; more efficient finite difference Hessians
- PSUADE generally available under LGPL
- Surfpack and LHS relicensed under LGPL
- DLL API improvements for re-entry, error handling, get/set options
- ModelCenter, MATLAB, and Python interface updates to latest API
- Updates to Matlab memory management
- HTTP-based usage tracking (disabled by default; currently used Sandia internally only)
- Windows: use spawn as alternative to fork