



# DAKOTA 101

## DAKOTA Overview

<http://dakota.sandia.gov/>

**Learning goals: Understand:**

- How DAKOTA interfaces with a simulation (computational model)
- DAKOTA input file structure; corresponding DAKOTA abstractions
- How to run DAKOTA and JAGUAR to perform parameter studies
- DAKOTA framework benefits

**Training materials can be viewed at:**

<http://dakota.sandia.gov/training/2011/>



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# DAKOTA Team Introductions



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# DAKOTA in a Nutshell



**Design and Analysis toolKit for Optimization and Terascale Applications** includes a wide array of algorithm capabilities to support engineering transformation through advanced modeling and simulation.

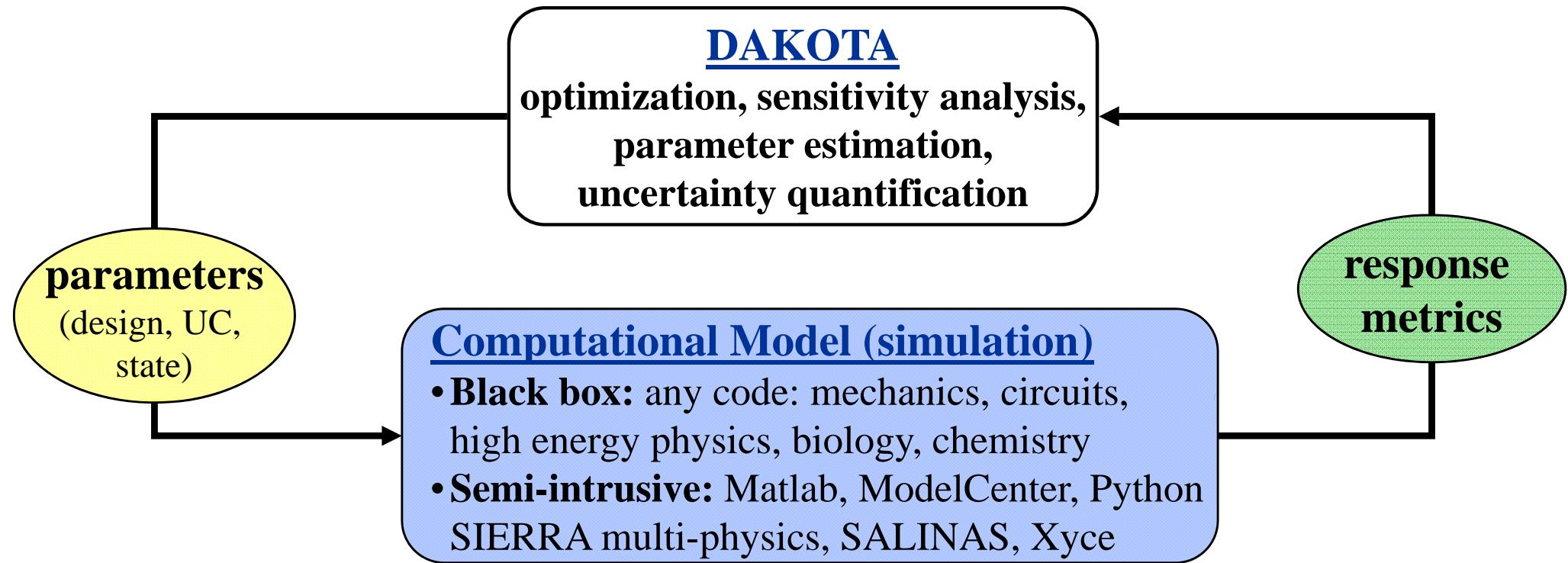
Adds value to simulation-based analysis by answering fundamental science and engineering questions:

- What are the crucial factors/parameters and how do they affect key metrics? (*sensitivity*)
  - How safe, reliable, robust, or variable is my system?  
(*quantification of margins and uncertainty: QMU, UQ*)
  - What is the best performing design or control? (*optimization*)
  - What models and parameters best match experimental data?  
(*calibration*)
- 
- *All rely on iterative analysis with a computational model for the phenomenon of interest*

# Automated Iterative Analysis



Automate typical “parameter variation” studies with advanced methods and a generic interface to your simulation



- **Can support experimental testing:** examine many accident conditions with computer models, then physically test a few worst-case conditions.



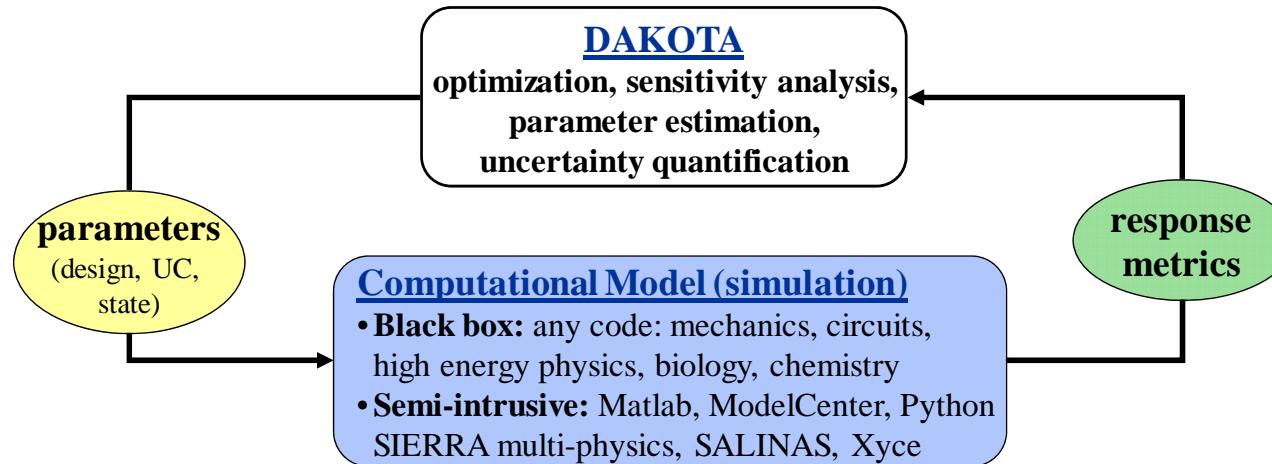
# Key DAKOTA Capabilities

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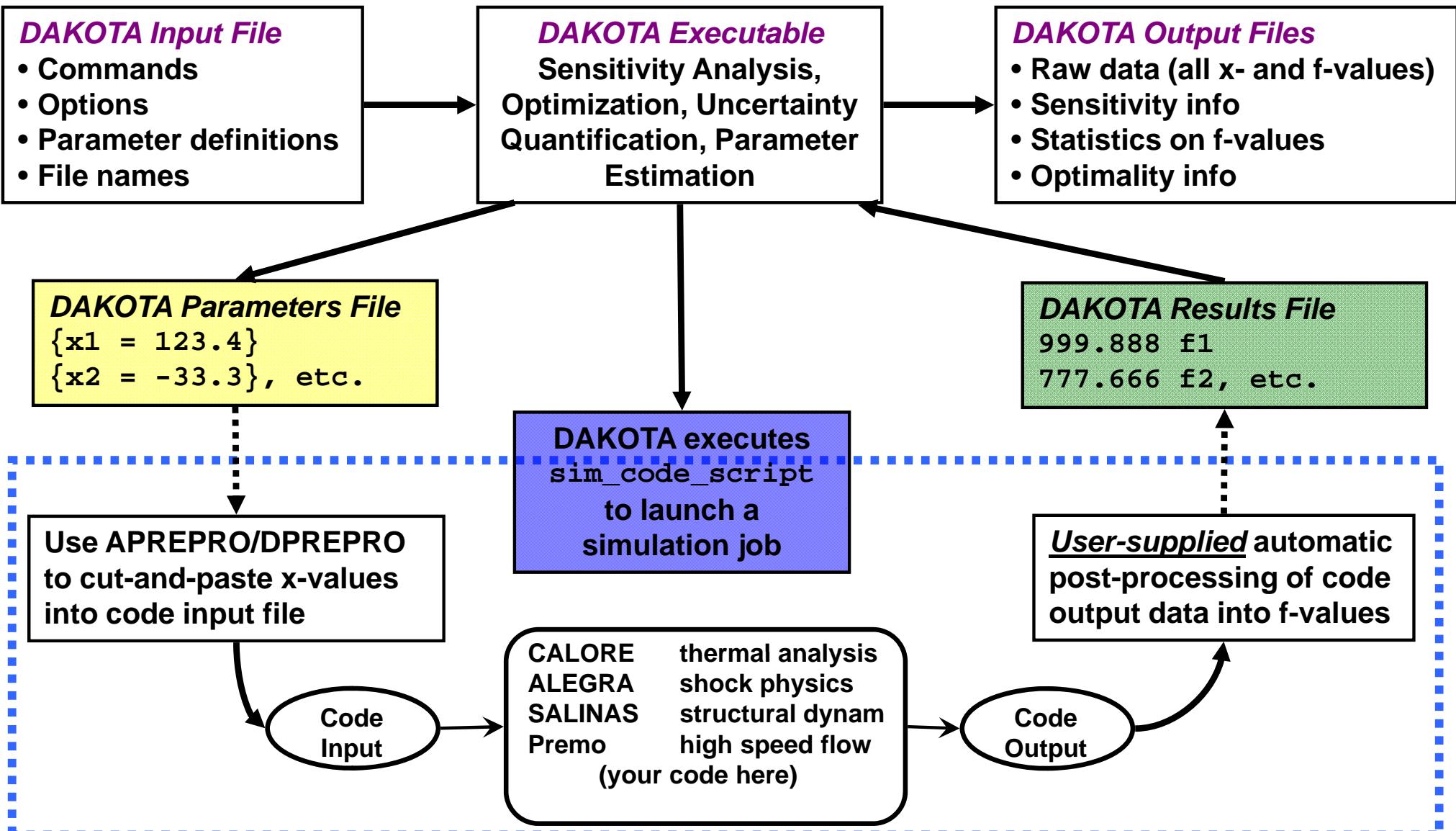
- Generic interface to simulations
- Time-tested and advanced algorithms to address non-smooth, discontinuous, multimodal, expensive, mixed variable, failure-prone
- Strategies to combine methods for advanced studies or improve efficiency with surrogates (meta-models)
- Mixed deterministic / probabilistic analysis
- Supports scalable parallel computations on clusters
- Object-oriented code; modern software quality practices
- Limited Windows interface (run via command prompt); however new graphical user interface. DART integration in progress.
- Additional details: <http://dakota.sandia.gov/>
  - Extensive documentation, including a tutorial
  - Support resources: <http://dakota.sandia.gov/resources.html>
  - Software downloads: stable releases and nightly builds (freely available worldwide via GNU LGPL)

# Overall DAKOTA 101 Goals



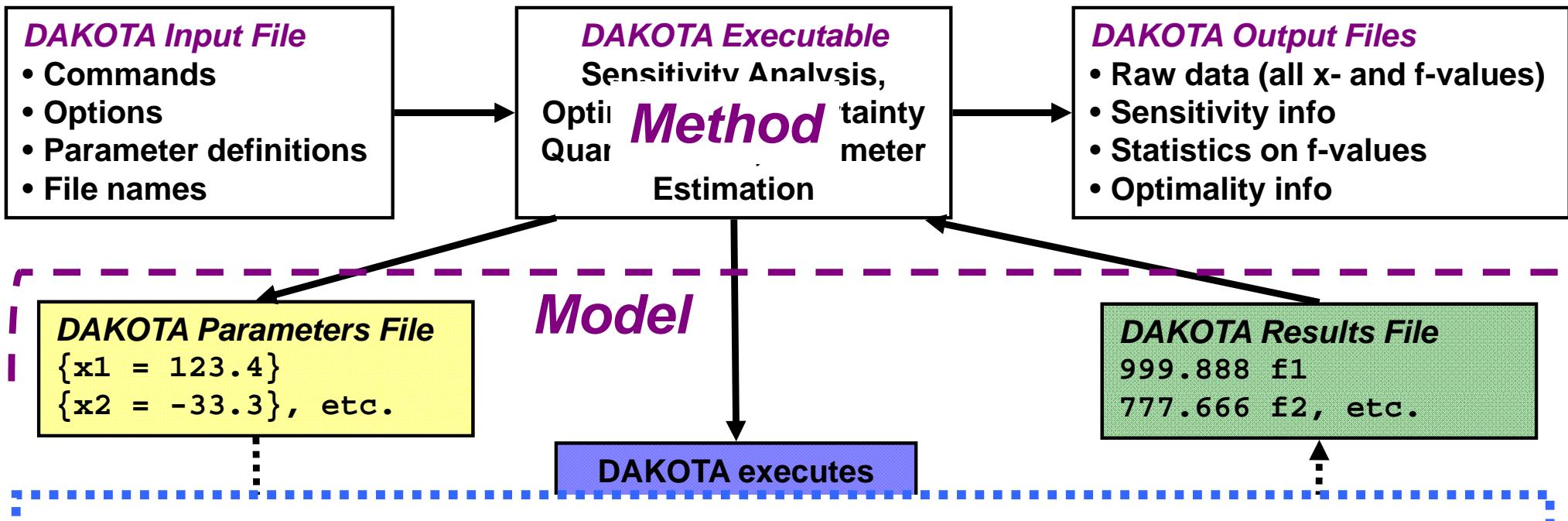
- DAKOTA 101 will focus on setting up various kinds of studies to drive this iterative flow
- We'll use JAGUAR GUI or text file editing to create input files, with command line run
- For this class we'll substitute test functions from the DAKOTA distribution for the simulation
- *DAKOTA Integration focuses on connecting to your actual application*

# DAKOTA Execution & Info Flow



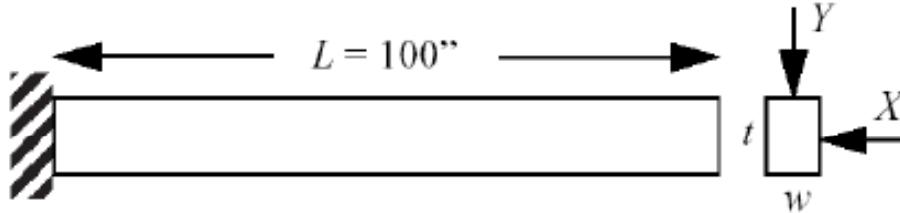
DAKOTA Application Interfacing Class

# DAKOTA Execution & Info Flow



Algebraic test function which “reads”  
parameters and writes results, e.g.,  
`rosenbrock`  
`text_book`  
`cantilever`

# Cantilever Beam Analysis Problem



- Design goal: minimize weight ( $A=w*t$ ) subject to constraints  
 $1.0 \leq \text{beam\_width} \leq 4.0$ ,  $1.0 \leq \text{beam\_thickness} \leq 4.0$ ,

$$\text{stress} = \frac{600}{wt^2} Y + \frac{600}{w^2 t} X \leq R$$

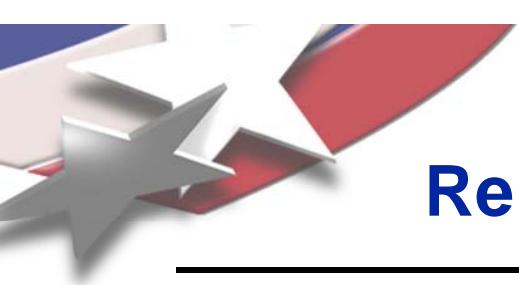
$$\text{displacement} = \frac{4L^3}{Ewt} \sqrt{\left(\frac{Y}{t^2}\right)^2 + \left(\frac{X}{w^2}\right)^2} \leq D_0$$

Given values of  $w$ ,  $t$ ,  $R$ ,  $E$ ,  $X$ ,  $Y$ , DAKOTA's mod\_cantilever driver computes area, stress- $R$ , displacement- $D_0$

- And potentially, subject to uncertainties:

– Yield stress	$R \sim \text{Normal}(40000, 2000)$
– Young's modulus	$E \sim \text{Normal}(2.9e7, 1.45e6)$
– Horizontal load	$X \sim \text{Normal}(500, 100)$
– Vertical load	$Y \sim \text{Normal}(1000, 100)$

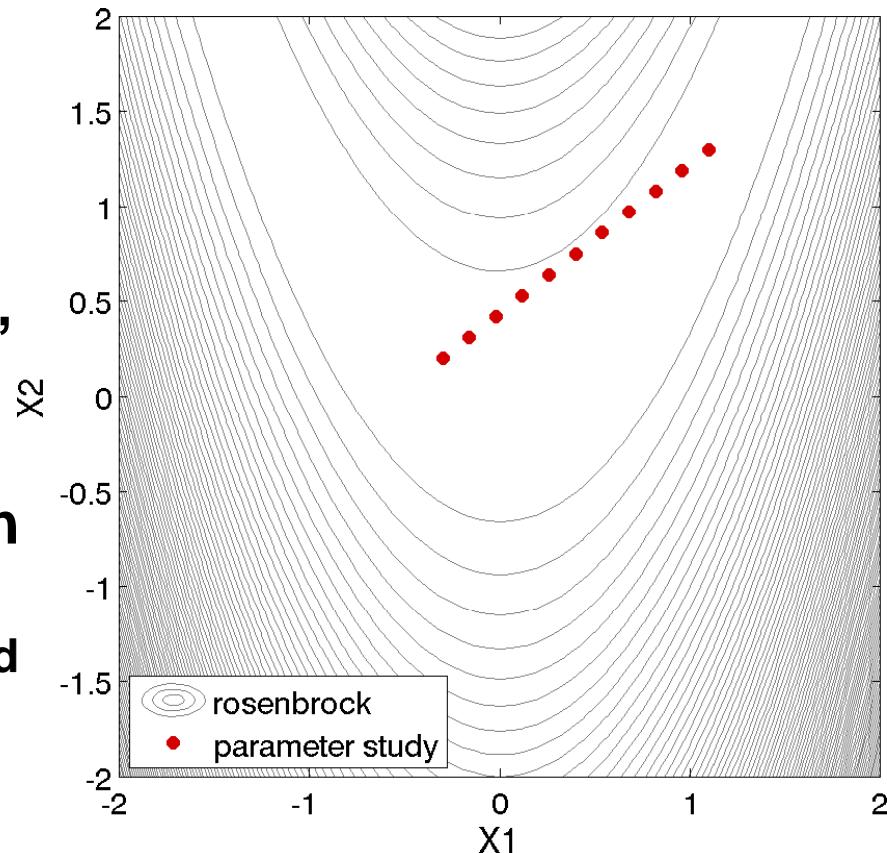
- Constants:  $L = 100\text{in}$  and  $D_0 = 2.2535 \text{ in}$  (max displacement)



# Exploring Parameter-Response Relationship: Vector Parameter Study



- **GOAL:** assess global trend of  $f(x_1, x_2)$  along a line in parameter space
- Example: 11 equally-spaced samples along a vector in the  $x_1$ - $x_2$  parameter space (based on start point, end point, number of samples)
- Not especially useful with  $N=2$ , but can be when  $N>2$ 
  - With large steps, provides some global trend info on function values
  - With small steps, provides some local trend info on f-values (quasi-derivatives)



See User's Manual Section 2.4.1.2



# Running a Vector Parameter Study

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- If using JAGUAR:
  - Start JAGUAR (Jaguar command) and set the DAKOTA executable location in Window > Preferences > Jaguar
  - Create a new file from template: “Parameter Study Vector”
- If using a text editor, copy to a location of your choice:  
`Dakota/examples/tutorial/dakota_rosenbrock_vector.in`
- Discuss the sections of this DAKOTA input file
- Verify the example runs (running in JAGUAR can be slower):
  - Use JAGUAR “Execute Problem” tab: “Check” and “Run”; or
  - Run `dakota -input myvector.in` from the command line (try `-check`)
- Modify this problem for cantilever (2 design, 4 state variables)
- See DAKOTA reference manual locally or at  
<http://dakota.sandia.gov/documentation.html>



# Input File: Vector Parameter Study



```
# DAKOTA INPUT FILE - dakota_rosenbrock_vector.in

strategy,
    single_method
    graphics,tabular_graphics_data

method,
    vector_parameter_study
    final_point = 1.1  1.3
    num_steps = 10

model,
    single

variables,
    continuous_design = 2
    initial_point    -0.3      0.2
    descriptors       'x1'      "x2"

interface,
    direct
    analysis_driver = 'rosenbrock'

responses,
    num_objective_functions = 1
    no_gradients
    no_hessians
```



# JAGUAR Guides Creation of Dakota Input Deck



## 6 potential sections (2 optional, 4 required):

### Define Problem

- Model (*optional*): single, surrogate (global, local, hierarchical), nested
- Variables (*required*): design, uncertain, and state variables; continuous/discrete
- Interface (*required*): system call, fork, or direct; specify parallel options
- Responses (*required*): number of responses/constraints, gradients, Hessian

### Define Flow

- Strategy (*optional*): *coordination of methods* single\_method, hybrid, multi\_start, pareto\_set
- Method (*required*): parameter studies, nondeterministic methods, optimization methods



# Optional Info: Flexibility with Models



***DAKOTA models map inputs to response metrics of interest:***

## variables/parameters

- design: continuous, discrete
- uncertain: (log)normal, (log)uniform, interval, triangular, histogram, beta/gamma, EV I, II, III
- state: continuous, discrete

## user application

(simulation)

system, fork, direct, grid

## optional approximation (surrogate)

- global (polynomial 1/2/3, neural net, kriging/Gaussian proc., MARS, RBF)
- local (Taylor); multipoint (TANA/3)
- hierarchical, multi-fidelity

## responses

- functions: objectives, constraints, LSQ residuals, generic
- gradients: numerical, analytic
- Hessians: numerical, analytic, quasi

*integrate parameters into  
application inputs*

*extract relevant metrics*

**For all DAKOTA studies, must specify the:**

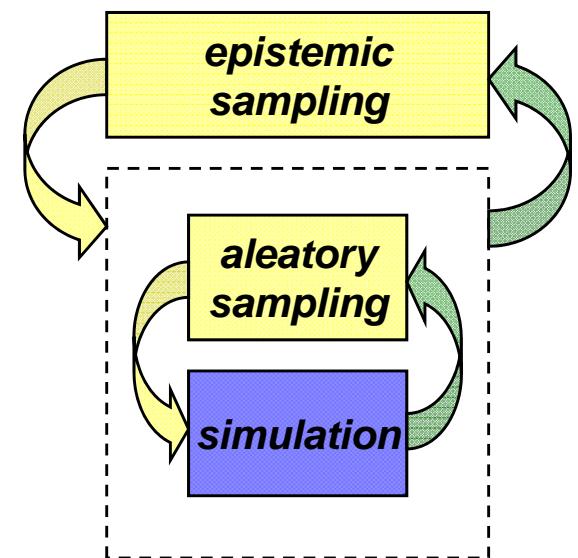
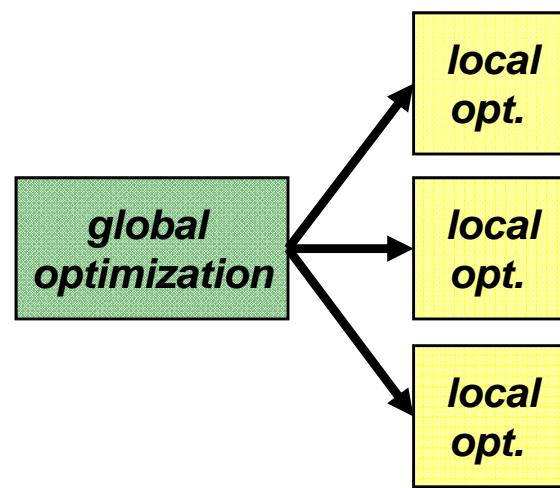
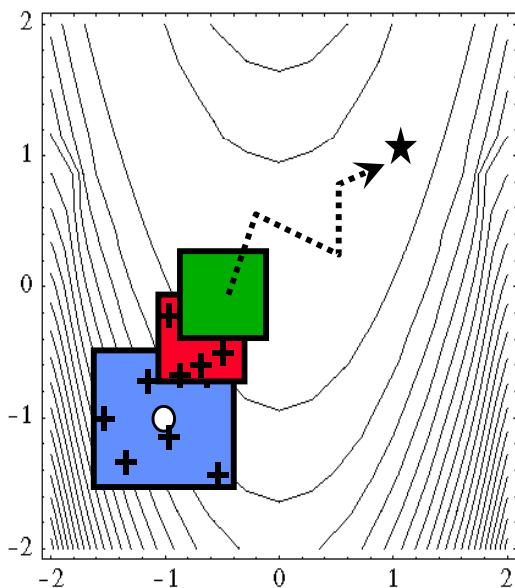
- variables of interest (types vary by study),
- interface that evaluates them
- responses it produces

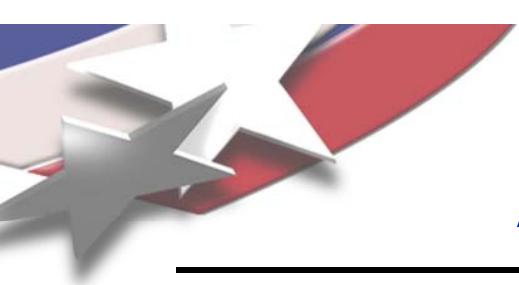
# Optional Info: Strategies (and advanced/multi-component methods)



**Strategies (nesting, layering, sequencing and recasting facilities) combine methods to enable advanced studies:**

- Combine optimization/calibration with uncertainty quantification
- Surrogate-based approaches
- Hybrid optimization
- Nested UQ



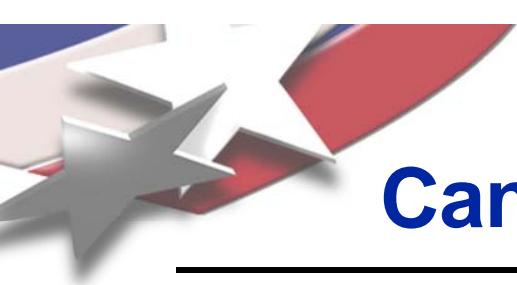


# Explore Cantilever Along a Vector in w-t Space



- Start with `dakota_rosenbrock_vector.in` (Parameter Study Vector)
- Modify to explore variables `beam_width` and `beam_thickness` on [1.0, 4.0]
- The `mod_cantilever` driver requires specification of all 6 variables, so add state variables to keep the uncertain variables fixed at means:

```
continuous_state = 4
initial_state 4000. 29.E+6 500. 1000.
descriptors      'R'    'E'    'X'    'Y'
```
- Add identical values to `final_point` so *R*, *E*, *X* and *Y* don't vary
- Change the `analysis_driver` to '`mod_cantilever`'
- Cantilever has 3 response functions, instead of 1; specify descriptors '`area`' '`stress`' '`displacement`'
- See DAKOTA reference manual: method, variables, responses commands  
(<http://dakota.sandia.gov/documentation.html>)



# Potential Solution: Cantilever Vector Parameter Study



```
# extraexamples/cantilever_vector.in

strategy,
    single_method
graphics, tabular_graphics_data

method,
    vector_parameter_study
        final_point = 4.0 4.0 40000. 29.E+6 500. 1000.
        num_steps = 10

variables,
    continuous_design = 2
        initial_point   1.0      1.0
        descriptors     'beam_width'    'beam_thickness'
continuous_state = 4
        initial_state   40000. 29.E+6 500. 1000.
        descriptors     'R'       'E'       'X'       'Y'

interface,
    direct
        analysis_driver = 'mod_cantilever'

responses,
    num_objective_functions = 3
        response_descriptors = 'area' 'stress' 'displacement'
no_gradients
no_hessians
```



# Dakota Execution and Output

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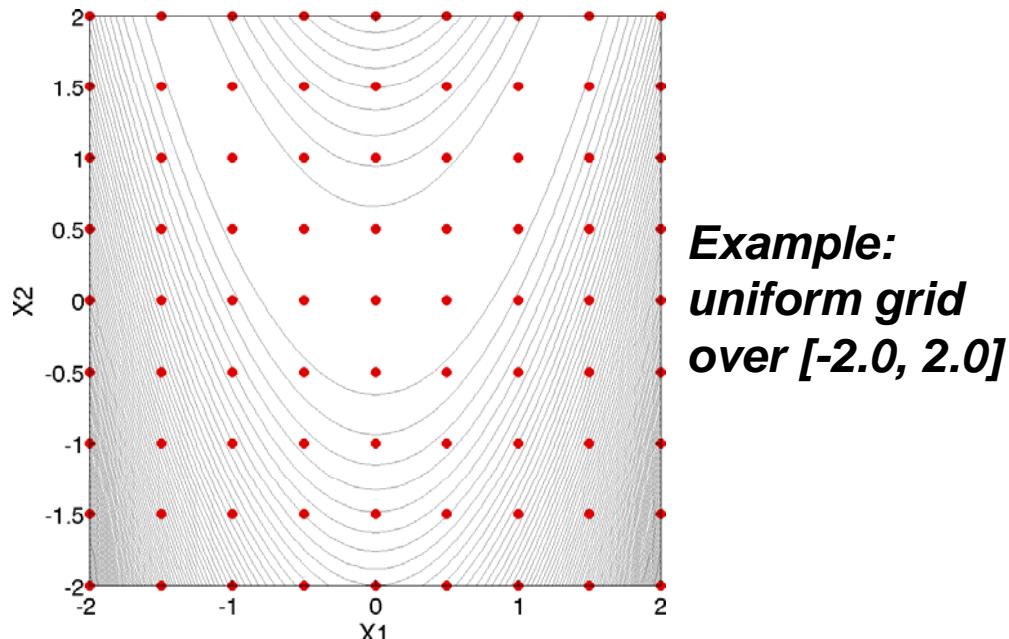


- DAKOTA is most commonly run from a UNIX or Windows command prompt
- Capture output: input variable and response information for each function evaluation; method-specific info  
`>> dakota -i my_run.in -o my_run.out`
- If strategy includes `tabular_graphics_data`, generates tabular listing of inputs and outputs, called `dakota_tabular.dat`. Useful for Excel, Matlab, or other package import.
- *Other command-line options*  
`>> dakota -help`

# Exercise: Multi-dimensional Parameter Study



- Goal: understand how responses *area, stress, and displacement* vary with respect to the inputs *w* and *t* on a grid of points.
- Exercise: change previous input file to run the *mod\_cantilever computational model* at a grid of points over [1.0, 4.0] using the *multidim\_parameter\_study method*
- Try 9 points in one dimension, 6 in the other
- See method and variable commands in DAKOTA reference manual
- What parts of the file did you have to change?





# Sample Input File: Multi-dimensional Parameter Study



```
# extraexamples/cantilever_grid.in
strategy,
single_method
graphics,tabular_graphics_data

method,
multidim_parameter_study
partitions = 9 6 0 0 0 0

variables,
continuous_design = 2
lower_bounds 1.0 1.0
upper_bounds 4.0 4.0
descriptors 'beam_width' 'beam_thickness'
continuous_state = 4
lower_bounds 40000. 29.E+6 500. 1000.
upper_bounds 40000. 29.E+6 500. 1000.
descriptors 'R' 'E' 'X' 'Y'

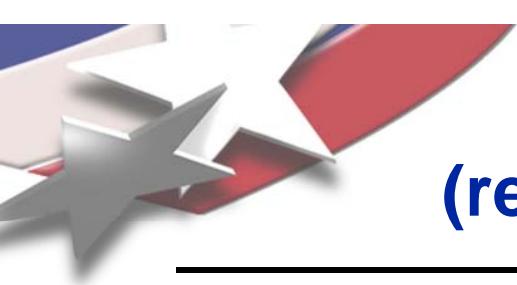
interface,
direct
analysis_driver = 'mod_cantilever'

responses,
num_objective_functions = 3
response_descriptors = 'area' 'stress' 'displacement'
no_gradients
no_hessians
```



## Method Tour

- Sensitivity Analysis
- Uncertainty Quantification
- Optimization and Calibration
- Advanced Topics per class interest and time



# Additional Topics (revisit later today per class interest)



## General features

- Restart
- Evaluation cache
- Utilities in `dakota_restart_util`
- Tabular graphics data
- Failure capturing: abort, retry, recover, ignore
- Constraint specification: linear, nonlinear; equality, inequality
- Input/output scaling
- Matlab interface

## Approximation methods

- Global data fit surrogate methods (polynomials, MARS, Kriging, etc.)
- Local surrogate methods (Taylor series, multipoint)
- Hierarchical: high/low fidelity models
- Corrections

## Strategies/Advanced approaches

- Nested models: OUU
- Multi-objective (Pareto) optimization
- Multistart; multi-level hybrid
- Surrogate-based optimization (variety of constraint handling approaches): trust region; EGO/EGRA
- Reliability-based design optimization
- Advanced UQ topics: polynomial chaos, second-order probability, Dempster-Shafer, surrogate-based UQ
- AMPL: for analytic problems / algebraic mappings

## Parallel capabilities: message passing, asynchronous local, hybrid

- Asynchronous evaluations
- Dakota parallel, application serial
- Dakota serial, application parallel
- Multi-level parallel: concurrent iteration, concurrent function evaluations, concurrent analyses,
- multiprocessor simulations



# Getting Started with DAKOTA



- Access a Sandia installation: module avail dakota  
**AMECH (CA), CEE (ESHPC/SCICO, NM), Computer clusters (both)**  
or download (see Analyst Home Page or DAKOTA webpage)
- Supported on Linux, Solaris, AIX (purple), Mac OS X, Windows (no MinGW or Cygwin install required), Redstorm
- Key resource: <http://dakota.sandia.gov>
  - Extensive documentation (user, reference, developer)
  - Support mailing lists / archives
  - Software downloads: releases and nightly stable & VOTD builds (freely available worldwide via GNU GPL)
- User's Manual, Chapter 2: Tutorial with example input files
- Support:
  - [dakota-users@software.sandia.gov](mailto:dakota-users@software.sandia.gov)  
(DAKOTA team and internal/external user community)
  - [dakota-help@sandia.gov](mailto:dakota-help@sandia.gov)  
(for SNL-specific or issues involving proprietary information)