



# DAKOTA 101

## DAKOTA Overview

<http://dakota.sandia.gov/>



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# DAKOTA 101

## Course Goals



**DAKOTA 101: Introduction to DAKOTA capabilities, application use cases, understanding its relevance for you. Understand major classes of algorithms, how to choose from among them, and create DAKOTA studies to execute them.**

***One day, 8:00—11:45, 1:30—5:00***

- 8:00 Overview of DAKOTA**
- 9:30 Parameter Studies and Sensitivity Analysis**
- 10:45 Uncertainty Quantification**
- 1:30 Optimization**
- 2:45 Calibration / Parameter Estimation from Data**
- 4:00 Wrap-up: best practices and teasers for advanced interfacing and algorithms**

***12:00—1:15: DAKOTA Brown Bag with experienced DAKOTA users.***

# Learning Goals: DAKOTA Overview



- Learn design and analysis processes DAKOTA supports; assess relevance in your domain
- Survey key algorithm classes available in DAKOTA; what differentiates it
- Requirements and process for getting started
- Tour the mechanics of running DAKOTA
- Know where to get help

# DAKOTA Supports



- **Simulation-based engineering design: optimize virtual (computational) prototypes**
- **Risk analysis and quantification of margins and uncertainty (QMU): assess the effect of parametric uncertainty on the probability of achieving desired system performance**
- **Verification and validation: automate mesh convergence or solver tolerance studies, generate ensembles of possible simulations or statistics to compare to experimental data**

# DAKOTA in a Nutshell



DAKOTA includes a wide array of algorithm capabilities to support engineering transformation through advanced modeling and simulation.

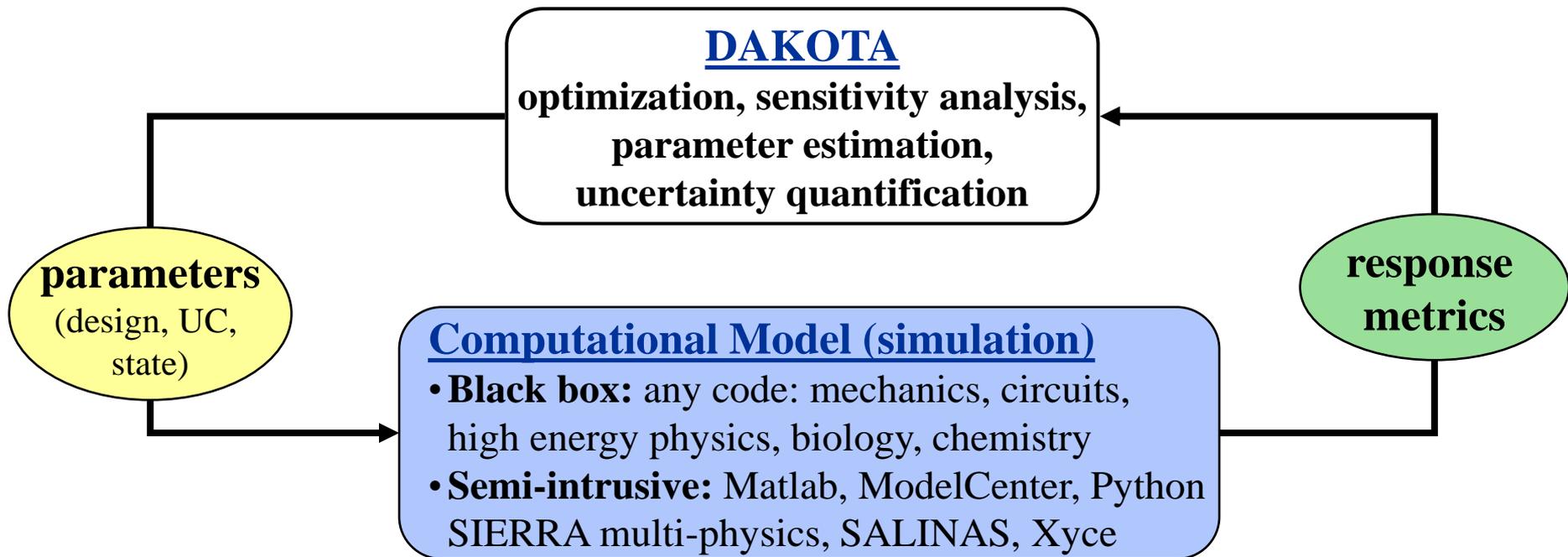
Adds value to simulation-based analysis by answering fundamental science and engineering questions:

- What are the crucial factors/parameters and how do they affect key metrics? (*sensitivity*)
- How safe, reliable, robust, or variable is my system? (*quantification of margins and uncertainty: QMU, UQ*)
- What is the best performing design or control? (*optimization*)
- What models and parameters best match experimental data? (*calibration*)
- *All rely on iterative analysis with a computational model for the phenomenon of interest*

# Automated Iterative Analysis of Computational Models

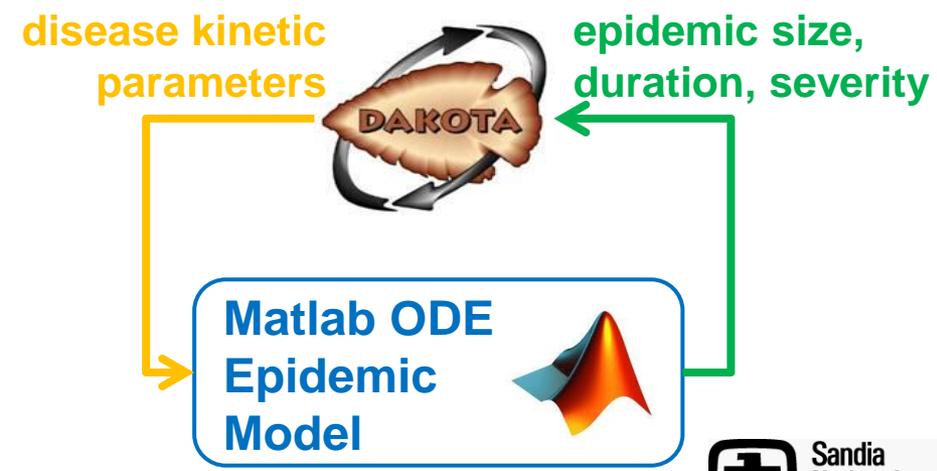
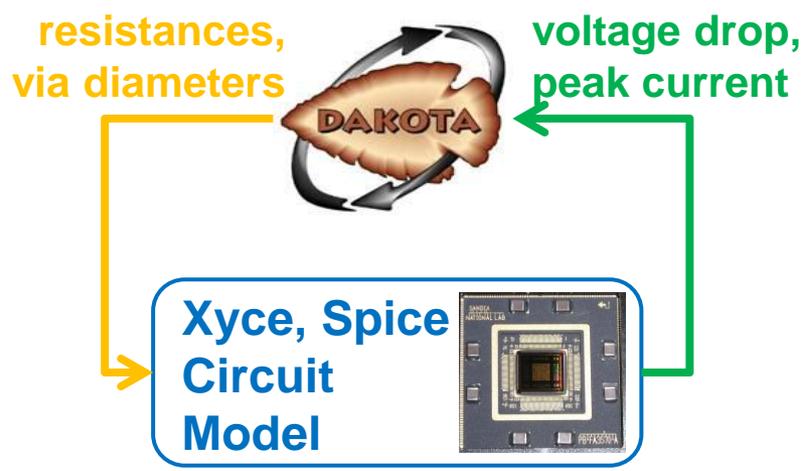
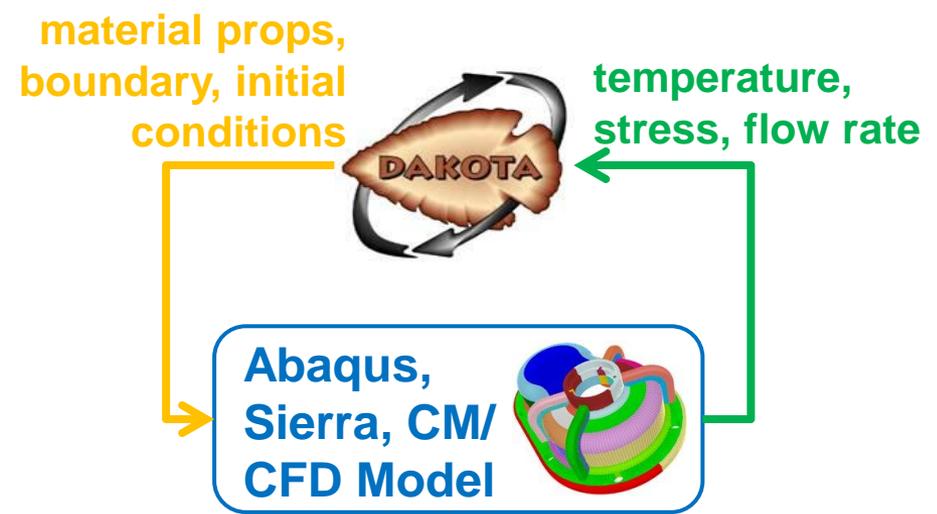
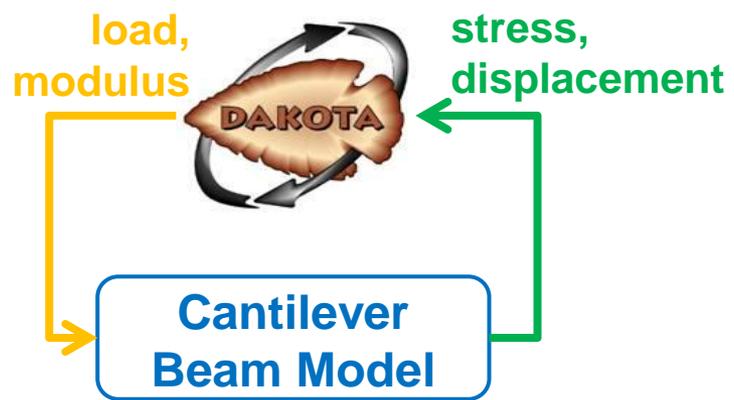


Automate typical “parameter variation” studies with various advanced methods and a generic interface to your simulation



- **Can support experimental testing:** examine many accident conditions with computer models, then physically test a few worst-case conditions.

# DAKOTA Analysis: Iterating over Parameters of Computational Models



# Simulation Challenges DAKOTA Addresses

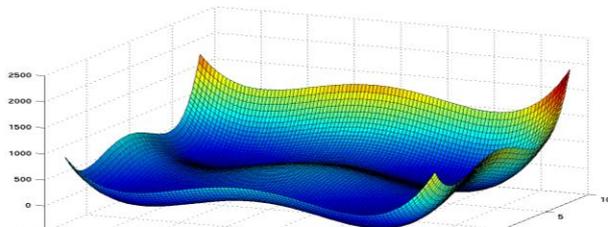
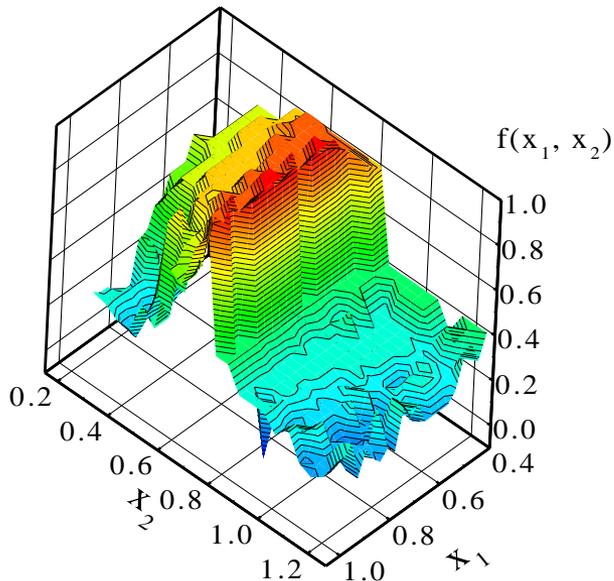
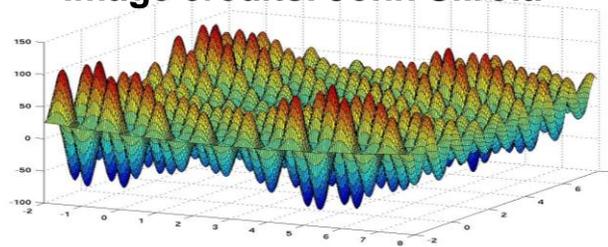


Image credits: John Sirola



In science and engineering problems of interest, we typically have:

- no explicit function for  $f(x_1, x_2)$ 
  - can't leverage algebraic structure
- limited number of evaluations/samples
  - expensive to evaluate  $f(x_1, x_2)$  (long runtime even on many processors)
  - simulation may fail (hidden constraints)
- noisy / non-smooth
  - can't reliably estimate derivatives
- local extrema, non-convex
  - globally optimal solutions challenging

*Considerable research has been done to mitigate these issues.*

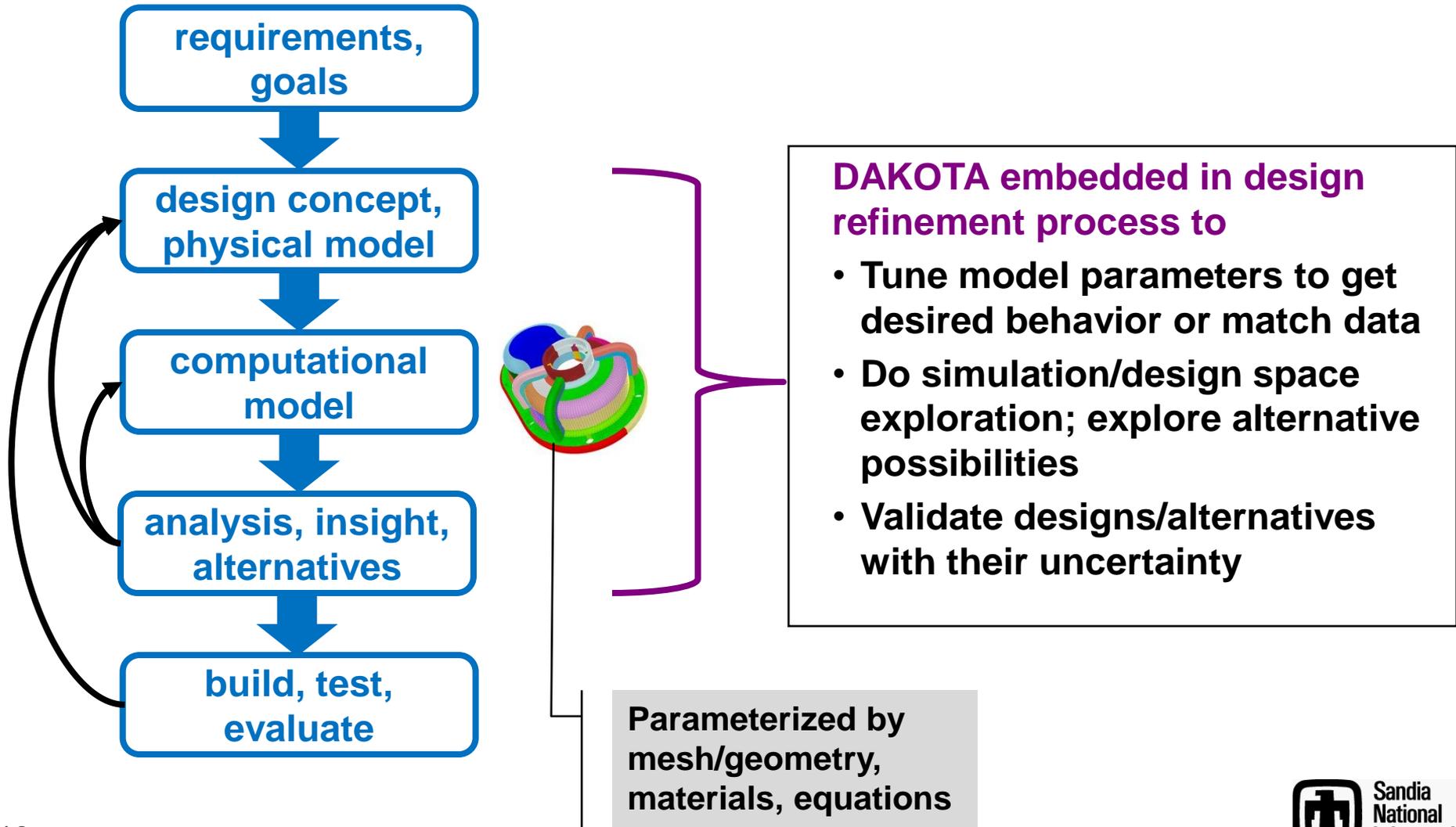
# Key DAKOTA Capabilities

## *Largely Addressed in Advanced Topics*



- **Generic interface** to simulations: parameters in, responses out
- **Time-tested and advanced research algorithms** to address challenging science and engineering simulations
- **Strategies to combine methods** for advanced studies or improve efficiency with surrogates
- **Mixed deterministic / probabilistic** analysis
- **Scalable parallel computations** from desktop to clusters
- **Primarily command-line and text-based interface;**  
**JAGUAR DAKOTA GUI and DART Workbench ease creating studies**
- **Object-oriented code; modern software quality practices**
- **Additional details:** <http://dakota.sandia.gov/>
  - Extensive documentation, including a tutorial
  - Support resources: <http://dakota.sandia.gov/resources.html>
  - Software downloads: stable releases and nightly builds  
(**freely available** worldwide via GNU LGPL)

# DAKOTA in (Simplified) Simulation-based Design Process



# Small Group Discussion: DAKOTA Relevance

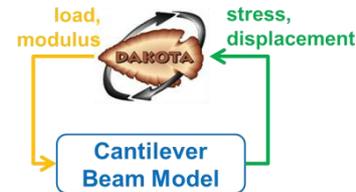


- **Discuss your initial impressions of DAKOTA's relevance for your problems**
- **With what kinds of applications, simulations, or computational models would you use it**
- **On what kinds of computer architecture would you want to use it  
(desktop workstation, Windows laptop, high-performance compute cluster)**

# Steps to Using DAKOTA

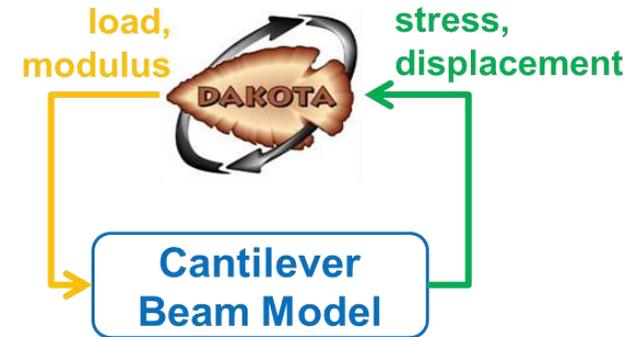
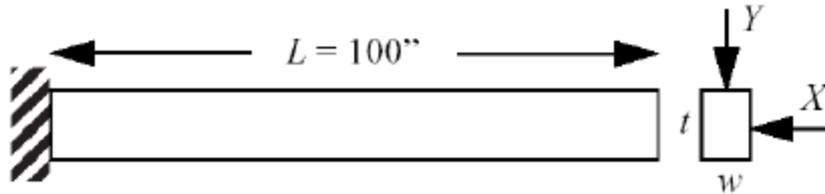


1. Define analysis goals; understand how DAKOTA helps, learn about and select from possible methods
2. Access DAKOTA and understand help resources
3. **Workflow:** create an automated workflow so DAKOTA can communicate with your simulation
  - Parameters to model, responses from model to DAKOTA
  - Typically requires scripting (Python, Perl, Shell, Matlab) or programming (C, C++, Java, Fortran)
  - Workflow usually crosscuts DAKOTA analysis types
4. **DAKOTA input file:** Jaguar GUI or text editor to configure DAKOTA to exercise the workflow to meet your goals
  - Tailor variables, methods, responses to analysis goals
  - Syntax documented in Reference Manual
5. Run DAKOTA: command-line; text input / output



*built-in cantilever  
beam analysis*

# Cantilever Beam Analysis Problem



- **Beam computational model:**

**weight (area =  $w*t$ )**       $stress = \frac{600}{wt^2} Y + \frac{600}{w^2 t} X \leq R$

**displacement**       $nt = \frac{4L^3}{Ewt} \sqrt{\left(\frac{Y}{t^2}\right)^2 + \left(\frac{X}{w^2}\right)^2} \leq D_0$

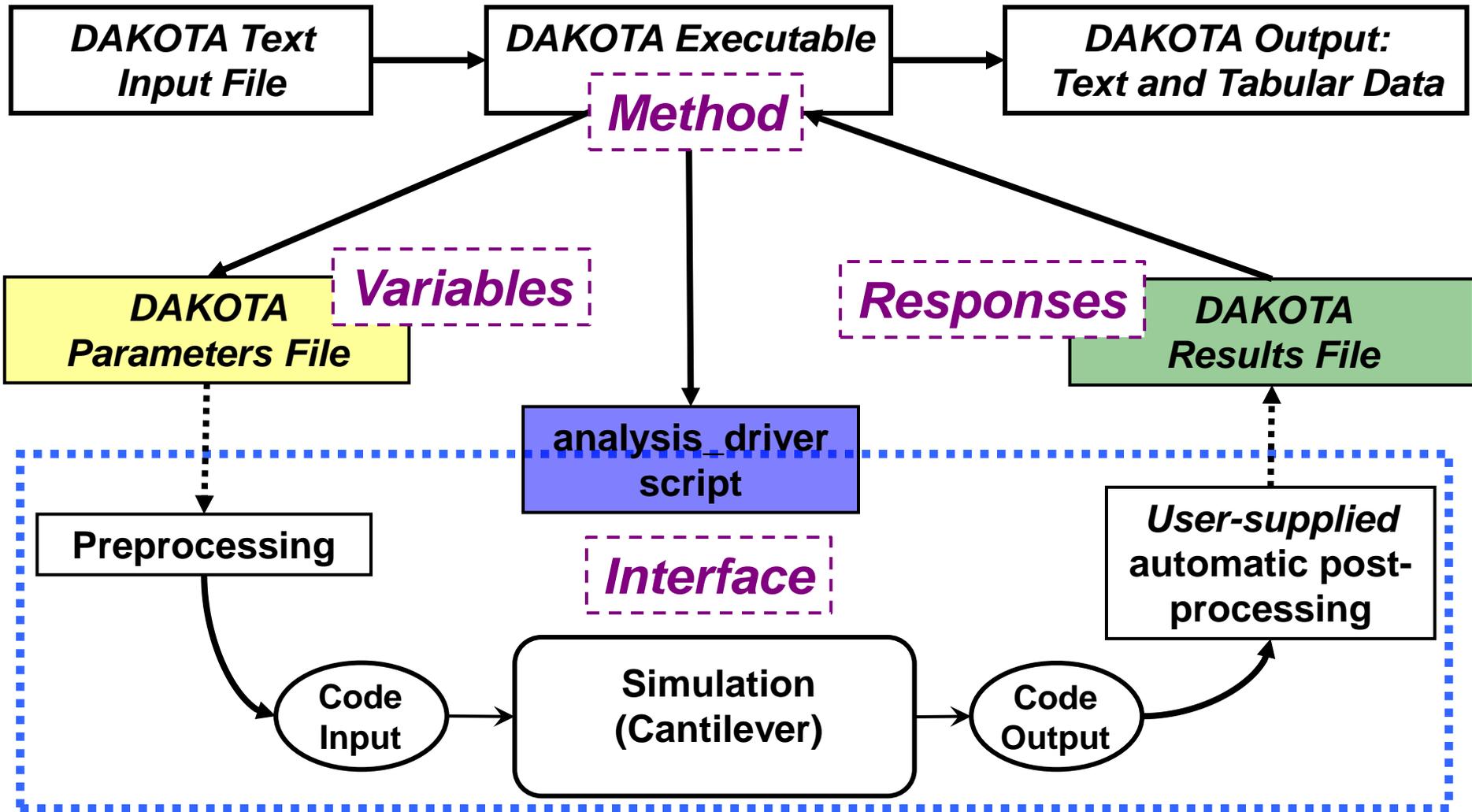
- **Definitions:**

- **t: thickness**       $1.0 \leq t \leq 4.0$
- **w: width**       $1.0 \leq t \leq 4.0$
- **R: yield stress**       $R \sim \text{Normal}(40000, 2000)$
- **E: Young's modulus**       $E \sim \text{Normal}(2.9e7, 1.45e6)$
- **X: horizontal load**       $X \sim \text{Normal}(500, 100)$
- **Y: vertical load**       $Y \sim \text{Normal}(1000, 100)$

**Given values of  $w, t, R, E, X, Y$ , DAKOTA's mod\_cantilever driver computes *area, stress-R, displacement- $D_0$***

- **Constants:  $L = 100\text{in}$  and  $D_0 = 2.2535\text{ in}$  (max displacement)**

# DAKOTA Execution & Info Flow



14 *What are examples of these for the cantilever beam problem?*

# Configure DAKOTA Input File for a Vector Parameter Study



```

strategy
  single_method
  graphics, tabular_graphics_data

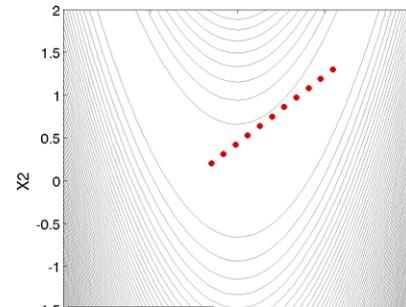
method
  vector_parameter_study
  num_steps = 10
  final_point 4.0 4.0 40000. 29.E+6 500. 1000.

variables
  continuous_design = 2
  initial_point 1.0 1.0
  descriptors 'beam_width' 'beam_thickness'
  continuous_state = 4
  initial_state 40000. 29.E+6 500. 1000.
  descriptors 'R' 'E' 'X' 'Y'

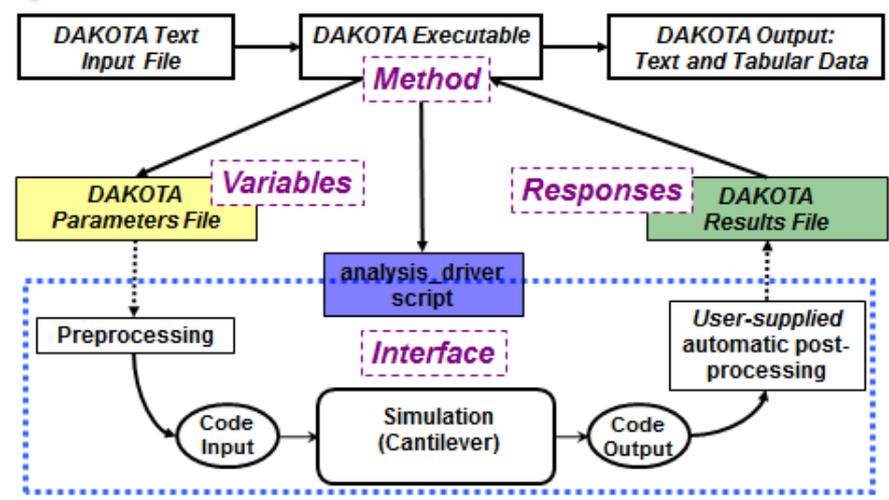
interface
  direct
  analysis_driver = 'mod_cantilever'

responses
  num_objective_functions = 3
  descriptors = 'area' 'stress' 'displacement'
  no_gradients
  no_hessians
  
```

*Define Flow / Algorithm*



## DAKOTA Execution & Info Flow



15



*Define Problem / Mapping*



# DAKOTA Input File: 4 Required, 2 Optional Sections



```
strategy
  single_method
  graphics, tabular_graphics_data

method
  vector_parameter_study
  num_steps = 10
  final_point 4.0 4.0 40000. 29.E+6 500. 1000.

variables
  continuous_design = 2
    initial_point 1.0          1.0
    descriptors   'beam_width' 'beam_thickness'
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    initial_state 40000. 29.E+6 500. 1000.
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interface
  direct
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responses
  num_objective_functions = 3
  descriptors = 'area' 'stress' 'displacement'
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  no_hessians
```

**strategy (opt):** coordinate hybrid methods and high level settings

**method (req):** specify iterative algorithm and settings

**variables (req):** parameters input to simulation; different types, domains for different studies

**interface (req):** map from variables to responses; control parallelism

**responses (req):** model output(s) to be studied

*Define Flow / Algorithm*

*Define Problem / Mapping*

**model (opt):** single, surrogate, nested

# Dakota Execution and Output



- **DAKOTA is most commonly run from a UNIX or Windows command prompt, also in Jaguar**
- **Capture output: input variable and response information for each function evaluation; method-specific info**  

```
>> dakota -i my_run.in -o my_run.out
```
- **strategy tabular\_graphics\_data: generates tabular listing of inputs and outputs, called dakota\_tabular.dat. Useful for Excel, Matlab, or other package import.**
- ***Other command-line options***  

```
>> dakota -help
```

# JAGUAR DAKOTA GUI



- Graphical user interface for creating, editing, and running DAKOTA input files (alternative to text editor)
- Java; based on Eclipse IDE/Workbench
- Windows, Mac, Linux support
- Beta integration in DART Workbench

## Key Features:



- Templates for common studies (most common starting point)
- Synchronized auto-completing text and hierarchical graphical editors
- Error checking and integrated help
- Sensitivity analysis, parameterization, and DAKOTA study wizards
- Basic visualization
- At SNL: job submission to clusters

# Getting Started and Getting Help



- Access a Sandia installation: `module avail dakota`  
*AMECH (CA), CEE (ESHPC/SCICO, NM), Computer clusters (both)*  
or download
- Supported on Linux/Unix, Mac OS X,  
Windows (no MinGW or Cygwin install required)
- Tour DAKOTA web pages: <http://dakota.sandia.gov>
  - Extensive documentation (*user, reference, developer*)
  - Support mailing lists / archives
  - Software downloads: official releases and nightly stable  
(freely available worldwide via GNU GPL)
- *User's Manual, Chapter 2*: Tutorial with example input files
- Support:
  - `dakota-users@software.sandia.gov`  
(DAKOTA team and internal/external user community)
  - `dakota-help@sandia.gov`  
(for SNL-specific or issues involving proprietary information)

# Advanced Capabilities Topics



## General features

- Restart
- Evaluation cache
- Utilities in `dakota_restart_util`
- Tabular graphics data
- Failure capturing: abort, retry, recover, ignore
- Constraint specification: linear, nonlinear; equality, inequality
- Input/output scaling
- Matlab interface

## Approximation methods

- Global data fit surrogate methods (polynomials, MARS, Kriging, etc.)
- Local surrogate methods (Taylor series, multipoint)
- Hierarchical: high/low fidelity models
- Corrections

## Strategies/Advanced approaches

- Nested models: OUU
- Multi-objective (Pareto) optimization
- Multistart; multi-level hybrid
- Surrogate-based optimization (variety of constraint handling approaches): trust region; EGO/EGRA
- Reliability-based design optimization
- Advanced UQ topics: polynomial chaos, second-order probability, Dempster-Shafer, surrogate-based UQ
- AMPL: for analytic problems / algebraic mappings

## Parallel capabilities: message passing, asynchronous local, hybrid

- Asynchronous evaluations
- Dakota parallel, application serial
- Dakota serial, application parallel
- Multi-level parallel: concurrent iteration, concurrent function evaluations, concurrent analyses,
- multiprocessor simulations

# Learning Goals: DAKOTA Overview



## *Were the DAKOTA Overview goals met?*

- Learn design and analysis processes DAKOTA supports; assess relevance in your domain
- Survey key algorithm classes available in DAKOTA; what differentiates it
- Requirements and process for getting started; do you see challenges?
- Tour the mechanics of running DAKOTA
- Know where to get help

## *What questions remain?*

# DAKOTA 101: Coming Up



## Method Tour

- Sensitivity Analysis
- Uncertainty Quantification
- Optimization
- Calibration / Parameter Estimation

## Advanced Topics teasers